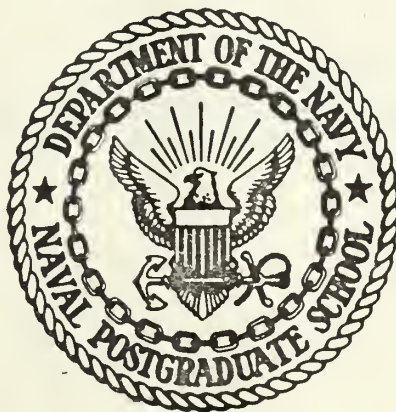


COMPUTERIZED AERODYNAMIC OPTIMIZATION  
OF  
AIRCRAFT PROPELLERS

Robert Linford Shaw



# United States Naval Postgraduate School



## THESIS

COMPUTERIZED AERODYNAMIC OPTIMIZATION  
OF  
AIRCRAFT PROPELLERS

by

Robert Linford Shaw

June 1970

*This document has been approved for public release and sale; its distribution is unlimited.*

1134516



Computerized Aerodynamic Optimization

of

Aircraft Propellers

by

Robert Linford Shaw

Lieutenant (junior grade) United States Navy  
B. S., Purdue University, 1969

Submitted in partial fulfillment of the  
requirements for the degree of

MASTER OF SCIENCE IN AERONAUTICAL ENGINEERING

from the

NAVAL POSTGRADUATE SCHOOL

June, 1970



### ABSTRACT

The objective of this thesis was to develop a practical computer system for use of empirical data in the aerodynamic optimization of aircraft propellers. The system was designed for use with the IBM 2741 on-line computer terminal. This program provides instructions to the operator during execution, and allows interaction by the operator for input and alteration of data, and for program instructions.

The Lockheed P-3C aircraft was chosen as the subject for test and evaluation of the program. The currently operational propeller of this aircraft was tested to compare the program's prediction of aircraft performance against flight test information. An attempt was then made to select a propeller which would provide better performance under the same constraints as those imposed in design of the operational propeller.





## TABLE OF CONTENTS

I.	INTRODUCTION . . . . .	9
II.	PROGRAM ORGANIZATION AND OPERATION . . . . .	12
	A. GENERAL ORGANIZATION . . . . .	12
	B. INPUT ROUTINE . . . . .	14
	C. OPTIMIZATION ROUTINE . . . . .	23
	D. PERFORMANCE EVALUATION ROUTINE . . . . .	31
III.	PROGRAM USAGE . . . . .	43
	A. OPTIMIZATION OF PROPELLERS FOR GIVEN AIRCRAFT . .	43
	B. EVALUATION OF A GIVEN PROPELLER CONFIGURATION . .	50
IV.	EXAMPLE PROBLEM: LOCKHEED P-3C . . . . .	51
	A. EVALUATION . . . . .	51
	B. OPTIMIZATION OF P-3 PROPELLER . . . . .	53
V.	EVALUATION OF PROJECT SUCCESS . . . . .	55
VI.	PROBLEMS ENCOUNTERED AND AREAS FOR FUTURE RESEARCH . .	56
APPENDIX A:	COMPUTER PROGRAM . . . . .	58
APPENDIX B:	SAMPLE COMPUTER OUTPUT . . . . .	90
	LIST OF REFERENCES . . . . .	102
	INITIAL DISTRIBUTION LIST . . . . .	103
	FORM DD 1473 . . . . .	105



## LIST OF TABLES

1.	P-3C DATA SHEET . . . . .	52
2.	COMPARISON OF FLIGHT TEST DATA AND PREDICTED PERFORMANCE OF P-3C AIRCRAFT . . . . .	53
3.	COMPARISON ON OPERATIONAL P-3C PROPELLER AND SAMPLE OPTIMUM PROPELLER . . . . .	54
4.	PREDICTED PERFORMANCE COMPARISON BETWEEN OPERATIONAL P-3 PROPELLER AND SAMPLE OPTIMUM . . . . .	54



## LIST OF FIGURES

1.	GENERAL PROGRAM ORGANIZATION . . . . .	13
2.	INPUT ROUTINE FLOW DIAGRAM . . . . .	15
3.	STARTING POINT ROUTINE . . . . .	21
4.	AEROPRODUCTS PRELIMINARY PROPELLER SELECTION CHART . . . . .	22
5.	OPTIMIZATION ROUTINE . . . . .	24
6.	EXPLORATORY STEP OF OPTIMIZATION ROUTINE . . . . .	25
7.	SEARCH PROCEDURE FOR NUMBER OF BLADES . . . . .	30
8.	AIRCRAFT PERFORMANCE EVALUATION ROUTINE . . . . .	33
9.	CALCULATION OF MAXIMUM VELOCITY AND CRUISE VELOCITY . . . . .	39
10.	CALCULATION OF CRUISE RATE . . . . .	42



## I. INTRODUCTION

In 1902, the Wright brothers, planning to adapt a theory used in the design of marine propellers, conducted a literature search in the Dayton, Ohio, public library. They found no theory, but only empirical data. A general theory of aircraft propeller performance was not forthcoming until 1929 in a paper presented to the Royal Society of London by Goldstein, [Ref. 1]. This "vortex theory" developed by Goldstein has since been revised and amplified [Ref. 2], but is still cumbersome and somewhat inaccurate for use in real propeller design.

Many wind tunnel tests were conducted on aircraft propellers before, during, and immediately following World War II, notably by Hartman and Biermann for the N.A.C.A. [Ref. 3]. Since that time the advent of the jet engine has caused a loss of interest in propeller research by all except a few propeller manufacturers.

Hence, even in 1970, aircraft propellers are still being designed by methods not much more sophisticated than those employed by the Wright brothers in 1902. A general theory exists which is limited in its applicability. Great volumes of empirical data, much of it useless in practice, has been generated. Still, however, the propeller designer basically searches through empirical charts for an aerodynamically optimum propeller configuration.

Hamilton Standard Division of United Aircraft, probably the leader in the field of propeller design, has estimated sixteen man-hours of this type of work for each propeller design. Some use was being made of modern digital computers, however, to choose the best design after the range of possibilities had been narrowed by the manual process. The programs used were reportedly based upon Goldstein's vortex theory of 1929.





The results of the extensive research and the general theories, in spite of the lack of sophistication, have been remarkable. The Wright brother's propeller, designed by a theory of their own, had an efficiency of about 66%. Modern propellers can be expected to exhibit efficiencies above 90%, in some cases.

Judging from the history of the past seventy years, it seems reasonable to assume that empiricism will continue to dominate the propeller field in the foreseeable future. Therefore, it is the purpose of this thesis to make the procedure of designing an aerodynamically optimum propeller a little easier, and less time consuming, by employing the on-line digital computer systems now available.

The result of this thesis was a computer program, PROPOP, designed for use with the IBM 2741 on-line computer console. PROPOP asks questions concerning the aircraft, engines, environment, constraints and optimization criteria. The required information is supplied by the operator through the communications console.

PROPOP was designed with the intent that it contain all the instructions needed by the operator to manipulate the program successfully. Parts II and III of this thesis serve as a user's manual, in case more detailed instructions on program use are required, or in the event the user wishes to modify the program in some way. Theoretically, no knowledge of FORTRAN or internal operation of the program is required for use of PROPOP, beyond the ability to use the IBM 2741 console (or similar system). Once execution of PROPOP begins, all instructions for its operation are provided by the program itself.

The advantages of PROPOP lie in the integration of propeller efficiency determination and aircraft performance evaluation. Present programs



apparently begin with assumed operating conditions for horsepower, altitude and velocity, then optimize propeller efficiency for these conditions. However, after this propeller is determined, it may be found that the aircraft does not actually operate at the assumed conditions. Consequently, the propeller is no longer optimum. The designer is then forced either to ignore this fact or to choose new assumed operating conditions and repeat the optimization process. In effect, PROPOP automatically chooses the latter of these two alternatives. Much flexibility is also incorporated into the system by allowing the operator to select the relative importance of the various aircraft performance characteristics, and by allowing him to impose constraints on aircraft performance.



## II. PROGRAM ORGANIZATION AND OPERATION

### A. GENERAL ORGANIZATION

As shown in Fig. 1, the complete program consists of three primary routines:

1. Input Subroutine
2. Optimization Subroutine
3. Performance Evaluation Subprogram

Immediately upon execution of the program, propeller performance data are read through the off-line card reader. These data are internal to the program. A message is typed on the operator's console when all data have been read. A brief explanation of the program is then printed, followed by a list of steps the operator must perform.

The Input Routine then begins. This routine asks questions of the operator about the aircraft, engines, etc., for which the propeller is to be optimized. The operator responds by typing in the required information and the program proceeds to the next question.

PROPOP operates in two modes. If the operator completely specifies the propeller during operation of the Input Routine, the program operates in the evaluation mode. In this mode the program proceeds from the Input Routine to the Performance Evaluation Routine (dashed line, Fig. 1) and evaluates the aircraft performance with the given specified propeller. However, should the operator leave any or all the propeller parameters unspecified, the program operates in the optimization mode. In this mode, after completion of the Input Routine, the program proceeds to the Optimization Routine and optimizes for the unspecified parameters (solid line, Fig. 1). The Optimization Routine repeatedly calls upon the Performance



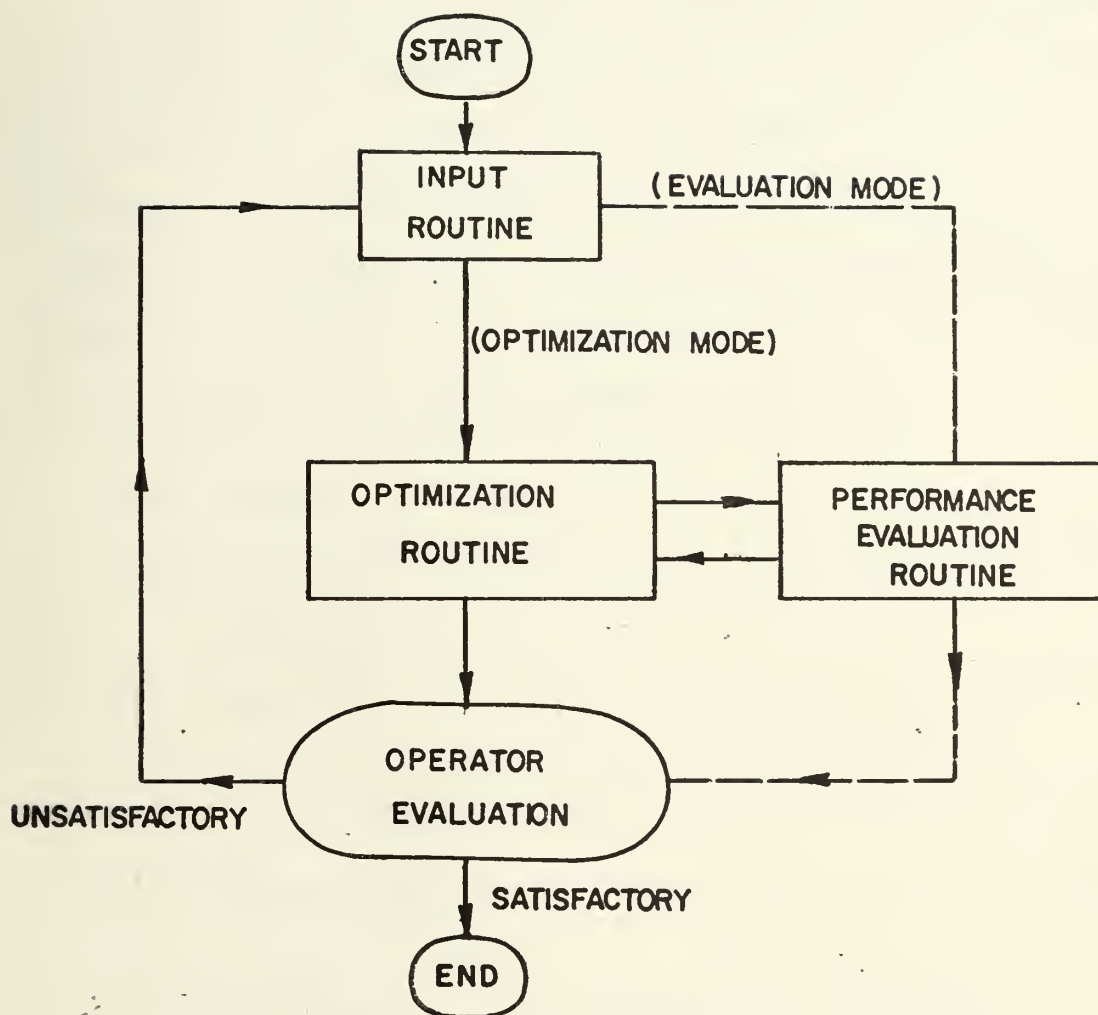


FIGURE 1  
GENERAL PROGRAM FLOW DIAGRAM.





Evaluation Routine for information needed in the optimization procedure. At its completion, the Optimization Routine prints the optimum propeller parameters as well as the aircraft performance with this propeller.

The next step in the procedure, regardless of the mode of operation, is evaluation of the output by the operator. At this point the operator may either terminate the program or he may return to the Input Routine and change any of the information that he has previously supplied. The usual action would probably be to change the constraints imposed on the aircraft or the propeller, or to change the priority given to any particular portion of the aircraft's mission.

#### B. INPUT ROUTINE

The Input Routine, Fig. 2, consists of seven input steps:

1. Aircraft data
2. Engine data
3. Aircraft environment and anticipated performance
4. Aircraft performance constraints
5. Propeller parameter constraints
6. Optimization criteria
7. End of routine (begin evaluation or optimization)

Each of the first six steps requires the operator to furnish data to the program by typing it into his terminal. Step 7 is only a reference point within the routine so that the operator can refer to the end of the routine by calling for Step 7. The broken lines without arrows in Fig. 2 indicate that the operator may skip from one step to another, either forward or backward, within the Input Routine. For instance, Step 4 and Step 6 are not required if the program is to operate in the evaluation mode, so these steps may be omitted altogether.



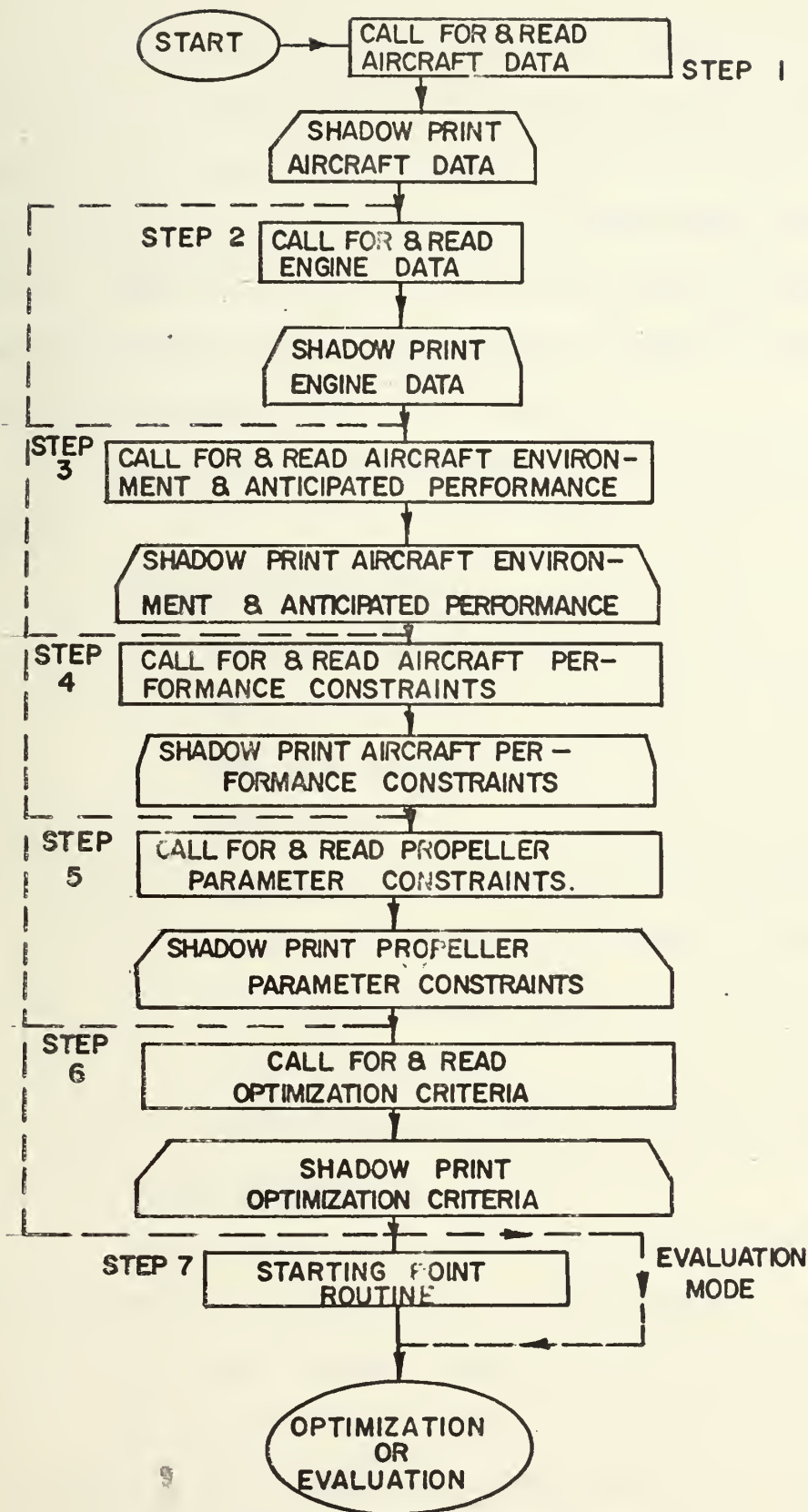


FIGURE 2  
INPUT ROUTINE FLOW DIAGRAM



In each of the first six steps, PROPOP asks the operator for information required by the program. The operator then types these data into his console. At the end of each step, all the data supplied by the operator are printed on the terminal so that the operator may check it for accuracy. Should any data be incorrect, the operator simply returns to the beginning of that step and begins again to answer the questions asked by the program, typing in the correct data.

The information called for by each step in the Input Routine is as follows:

1. Step 1 (Aircraft Data)

- a. Design gross weight (lbs.)
- b. Wing area (sq. ft.)
- c. Number of engines
- d. Aspect ratio
- e. Parasitic drag coefficient (takeoff configuration)
- f. Parasitic drag coefficient (cruise configuration)
- g. Wing efficiency factor (e)
- h. Fuel capacity (lbs.)
- i. Takeoff speed (kts. TAS)

2. Step 2 (Engine Data)

Engine data required by this step are determined by whether the aircraft uses reciprocating or turbine engines.

- a. Type of Engine (Reciprocating or Turbine)
- b. Reciprocating Engine
  - (1) Takeoff brake horsepower
  - (2) Engine RPM during takeoff
  - (3) Brake horsepower during climb



- (4) Engine RPM during climb
- (5) Brake horsepower during cruise
- (6) Engine RPM during cruise
- (7) Brake horsepower at maximum aircraft speed
- (8) Engine RPM at maximum aircraft speed
- (9) Fuel consumption (per engine) during cruise (lbs/hr)

c. Turbine Engine

- (1) Engine operating RPM
- (2) Shaft horsepower (per engine) at cruise altitude and cruise power, for anticipated cruise speed and for 50 kts. above this speed
- (3) Shaft horsepower (per engine) at maximum power setting (power for takeoff and maximum speed) and at 10,000 ft. MSL
- (4) Sea level shaft horsepower (per engine) for maximum power setting at zero, 100, and 400 kts. TAS
- (5) Sea level jet thrust (per engine) for maximum power setting at zero, and 100 kts. TAS
- (6) Sea level jet thrust for cruise power setting at zero and 100 kts. TAS
- (7) Fuel consumption (lbs/hr) per engine for cruise power and altitude, at anticipated cruise speed and 50 kts. above this speed
- (8) Limiting shaft horsepower for continuous operation

All data requested for reciprocating engines should correspond to the referenced aircraft operating conditions. For example, "cruise horsepower" should be given for cruise RPM, cruise altitude and anticipated cruise speed. All conditions are specified above for turbine engines.





All engine data are for the installed engine. Shaft horsepower (Item 4) for the turbine engine should be entered without regard to maximum allowable SHP due to gear box restrictions, etc. In other words, SHP's in Item (4) above may be greater than maximum allowable SHP in practice. This is necessary because of the interpolation process employed by the program. However, SHP's greater than the maximum allowable SHP are not actually used in calculating aircraft performance.

3. Step 3 (Aircraft Environment and Anticipated Performance)

- a. Takeoff altitude
- b. Cruise altitude
- c. Altitude for maximum speed calculations
- d. Anticipated speed for best climb rate (TAS)
- e. Anticipated cruise speed (kts. TAS)
- f. Anticipated maximum speed (kts. TAS)

The altitudes specified above are those at which aircraft performance is calculated and are reference altitudes for much of the engine data requested in Step 2. The anticipated speeds are again reference points for engine data, but are also starting points for the iterative process employed by the computer to calculate aircraft performance.

4. Step 4 (Aircraft Performance Constraints)

This step is required only for optimization of a propeller, not for simple evaluation of a given propeller.

- a. Maximum allowable takeoff distance (ft)
- b. Lowest allowable maximum climb rate (ft/min)
- c. Minimum allowable range at cruise conditions (n. mi.)
- d. Minimum allowable endurance at cruise conditions (hrs)



e. Minimum allowable cruise speed (kts. TAS)

f. Lowest allowable maximum speed (kts. TAS)

5. Step 5 (Propeller Constraints)

a. Maximum blade diameter for structural or ground clearance  
(ft)

b. Number of blades (2, 3, or 4)

c. Gear ratio (engine RPM/prop RPM)

d. Blade diameter (ft)

e. Activity factor (80-220 except for 2 blades, then 80-120)

f. Integrated lift coefficient (.15-.7 or .3-.7 for 2 blades)

Although this step is required for both the evaluation and the optimization mode of PROPOP, only the first item (maximum blade diameter) must be specified. Any or all of the other items may be left open to optimization by typing zero (0.) after the request for that particular item. If any of these items is left unspecified in this manner, the program automatically operates in the optimization mode. Should all the items be specified, the program operates in the evaluation mode. The limits of the data currently available to the program are indicated above.

6. Step 6 (Optimization Criteria)

This step is required only for the optimization mode.

a. Value of importance of short takeoff distance

b. Value of importance of climb rate

c. Value of importance of range

d. Value of importance of endurance

e. Value of importance of cruise speed

f. Value of importance of maximum speed

"Values of Importance" are numbers from zero to ten indicating the



relative value of a particular aircraft performance characteristic to the overall aircraft mission. The absolute value of these numbers is not critical, only the relative values. Where more than one performance characteristic is given a non-zero value, the Optimization Routine stresses the characteristics in the order of their values, the highest value receiving highest priority.

The "Starting Point Routine" (Fig. 3) is designed for use in the optimization mode of PROPOP. Its purpose is to make an intelligent guess at the optimum propeller configuration before the actual optimization procedure begins. This is necessary for three reasons. First, the Optimization Routine must begin somewhere and the closer it begins to the final optimum the better. Secondly, the procedure must start within the range of propeller data available. The optimization procedure itself forces the propeller to lie within the range of data after the procedure begins. The third, and probably most important reason, is that the first propeller configuration chosen should be one with which the aircraft can fly. For example, it is difficult for the program to determine which propeller parameter to change for an improvement in cruise speed if the aircraft cannot even takeoff with the starting propeller. In such a case PROPOP attempts to optimize climb rate in order to find a propeller with which the aircraft will fly. This procedure is, however, subject to possible failure.

The basis of the Starting Point Routine is the Aeroproducts Preliminary Propeller Selection Chart, a generalized copy of which is shown in Fig. 4. The data in this chart are included in PROPOP and have the effect of introducing an "experience factor" into the Starting Point Routine.



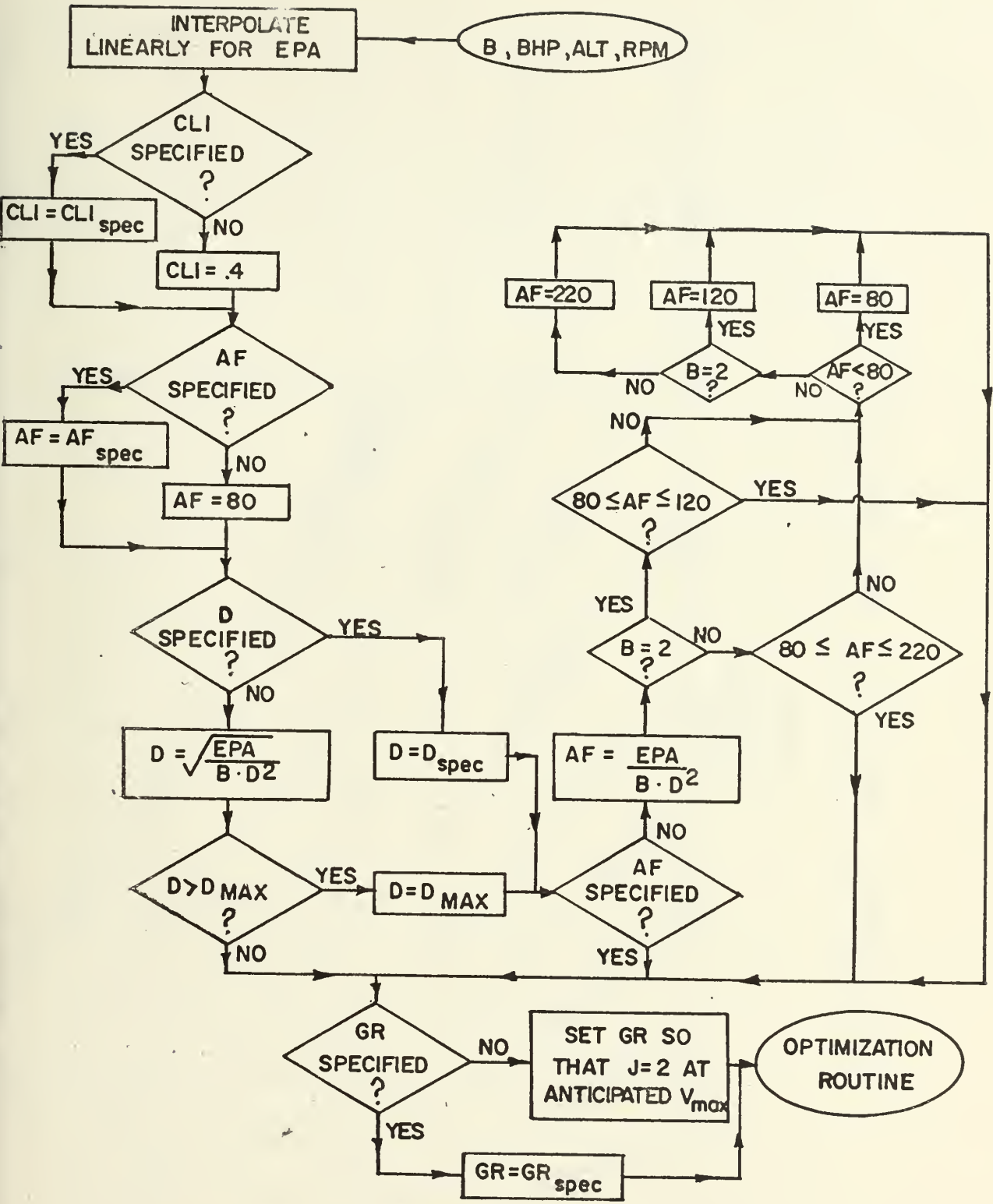


FIGURE 3  
STARTING POINT ROUTINE





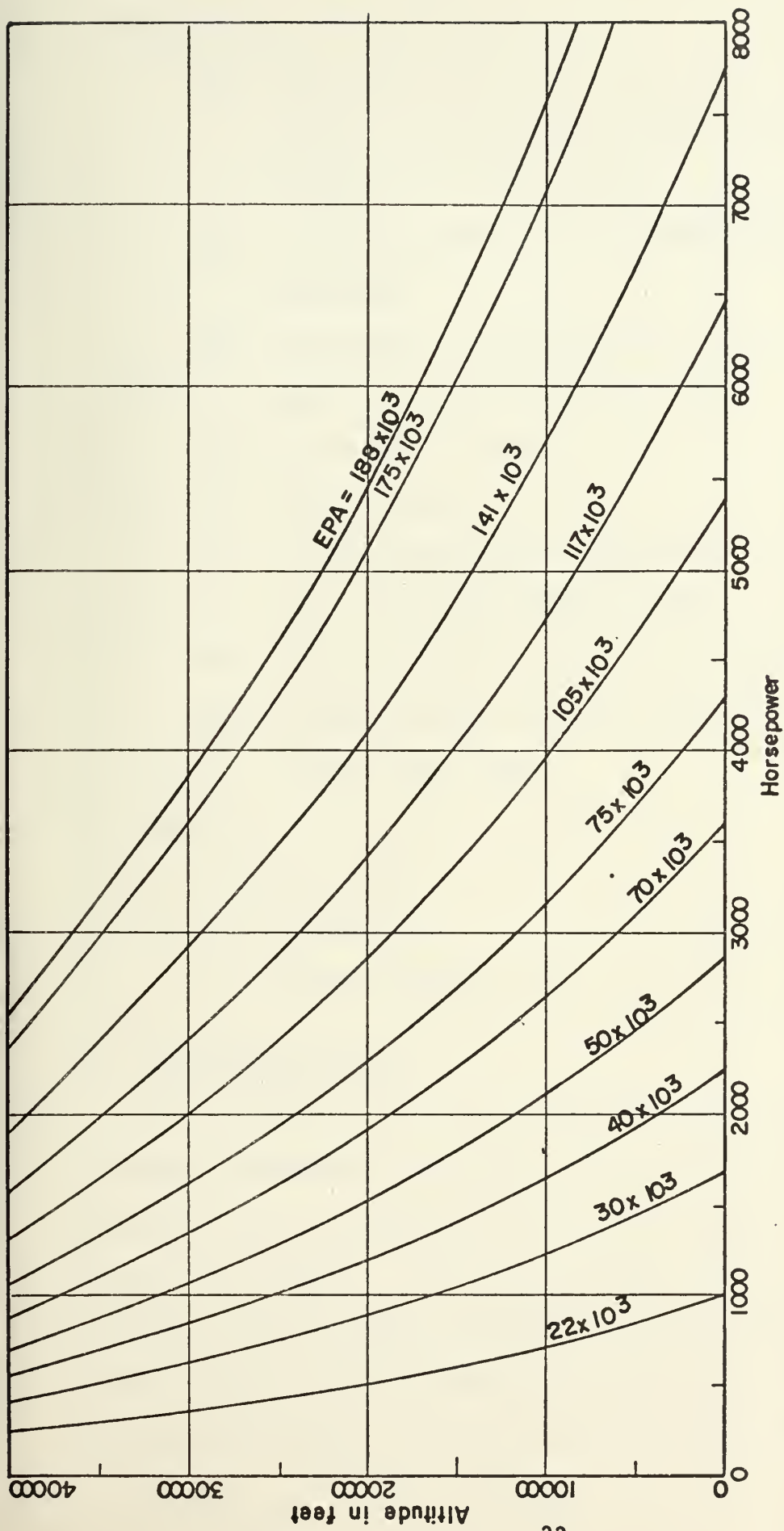


FIGURE 4

AEROPRODUCTS PROPELLERS — PRELIMINARY SELECTION



Explanation of terms in Fig. 3:

BHP - brake/shaft horsepower; horsepower specified for maximum velocity for reciprocating engine, maximum continuous horsepower for turbine engine

ALT - altitude at which maximum aircraft speed is to be evaluated

RPM - engine RPM at maximum aircraft velocity

B - number of propeller blades per engine

AF - blade activity factor

D - blade diameter

CLI - blade integrated lift coefficient

GR - gear ratio (engine RPM/prop RPM)

EPA - effective propeller area ( $B \times AF \times D^2$ ) from Fig. 4.

DMAX- maximum allowable propeller diameter

J - advance ratio ( $v/nd$ )

where:

$v$  = TAS, ft/sec

$n$  = propeller RPS

$D$  = Propeller diameter, ft.

### C. OPTIMIZATION ROUTINE

The optimization procedure is based on a pattern search technique developed by Hooke and Jeeves [Ref. 4, 5]. The subroutine DIRECT, incorporated into the IBM System/360 Subroutine Library in 1966 was used as the basic optimizer. It is this procedure which is outlined in Figs. 5 and 6. This subroutine is, however, an unconstrained minimization program. For this reason the routine had to be heavily modified so that it could handle the highly constrained propeller optimization problem.



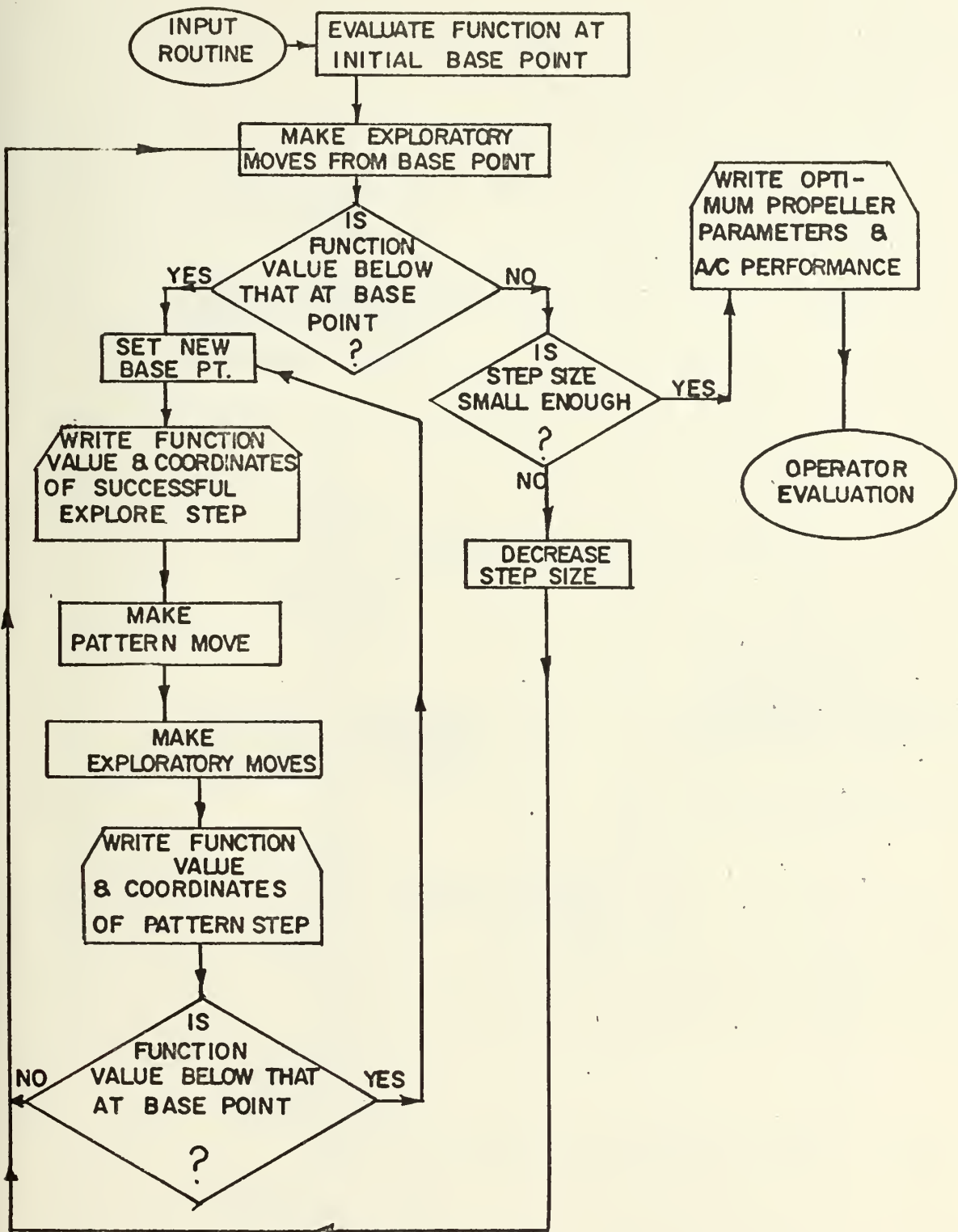


FIGURE 5  
OPTIMIZATION ROUTINE



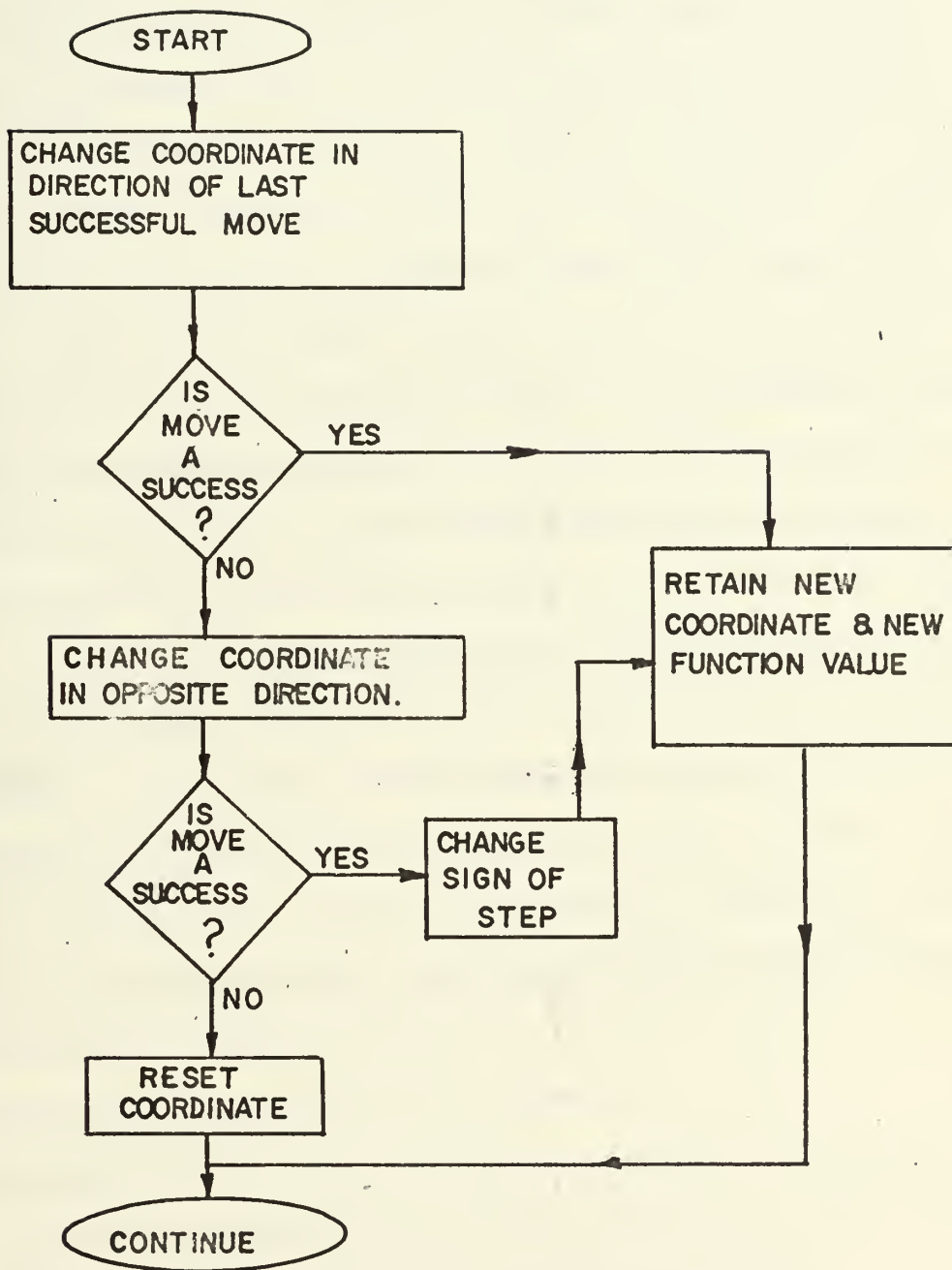


FIGURE 6  
EXPLORATORY STEP OF OPTIMIZATION ROUTINE.





Basically, pattern search is a numerical trial-and-error procedure closely akin to the better known "gradient search" methods [Ref. 6]. A fundamental difference, however, is that pattern search, unlike gradient methods, does not attempt to follow the path of steepest descent to the minimum of the function value. It is this very property which often foils gradient methods when they encounter a "ridge" or "steep valley" in the objective function. The pattern search begins by exploring the region of the starting (base) point by incrementing each variable separately in search of a function value which is better (lower in this case) than the base point (Fig. 6). After having explored in all the separate variable directions, the program will have normally found a better function value than the base point value. It then assumes that further decreases in the function value may be made in this same direction from the base point (Fig. 5). The program has now established a "pattern" and will continue to make pattern moves in this direction until a move fails to produce an improvement. At this point another exploratory sequence is performed and the procedure begins again. If all exploratory steps also fail to produce an improvement, the step size is decreased to increase the definition of the functional surface. The program terminates when the step size falls below a prescribed value.

Modification of this subroutine included built-in "stops" to insure that the search procedure does not leave the bounds of the available data. Other modifications allowed the operator to specify any of the variables so that the search procedure does not change these variables. The specified variables are known as equality constraints because they are always equal to a set value. Constraints which specify a range or a limit of



acceptable values of the variables, such as the data limits, are known as inequality constraints.

Another set of important inequality constraints are the aircraft performance constraints. These constraints were accomplished by modifications of the Performance Evaluation Routine rather than the optimization procedure itself. If at any time the propeller variables being tested by the Optimization Routine result in aircraft performance which is unacceptable by the operator's prescribed standards, a false function value is assigned for that trial. This false function value is designed so that it decreases very rapidly as the "boundary of acceptance" of the aircraft performance is approached.

In order to understand the operation of this technique more clearly, it is necessary to have an explanation of the way in which a functional value of aircraft performance is derived. The technique employed by PROPOP is as follows. For a given propeller configuration the performance of the aircraft is evaluated by the Evaluation Routine. A functional value (which has been derived by the author) is then assigned. This value has the form:

$$F = \sum_i [(VOI)_i \cdot P_i + N_i \cdot P'_i]$$

where

$F$  is the functional value

$i$  is an index denoting one of the performance criteria (takeoff distance, maximum speed, etc.)

$(VOI)_i$  is the value of importance assigned by the operator to the  $i^{th}$  performance criterion

$P_i$  is a normalized measure of the  $i^{th}$  performance criterion which always decreases as the  $i^{th}$  performance criterion improves



( $P_i$  is of order 1)

$N_i$  is simply an indicator which equals zero if the  $i^{\text{th}}$  criterion is acceptable and equals one if the  $i^{\text{th}}$  criterion is unacceptable

$P_i'$  is another measure of the  $i^{\text{th}}$  performance criterion which decreases as the  $i^{\text{th}}$  criterion improves, but  $P_i'$  is of order 100 or greater.

The Optimization Routine seeks to reduce the value of  $F$ , so as long as each performance criterion meets the constraints imposed by the operator, the routine attempts to decrease the value of  $P_i$  and consequently improve the  $i^{\text{th}}$  performance criterion. Because all  $P_i$  are of order one, a high value of  $(VOI)_i$  gives more weight to the  $i^{\text{th}}$  criterion in the overall function. However, if one or more of the constraints is not satisfied, then  $N_i$  equals one, which allows  $P_i'$  to dominate the other terms of the function. The optimizer immediately goes to work on improving the  $i^{\text{th}}$  criterion until the boundary of acceptance is crossed, at which time the routine continues to optimize the  $P_i$  values giving preference to higher values of importance.

Five variables are recognized by the Optimization Routine. These are:

1. Number of blades
2. Gear ratio (engine RPM/prop RPM)
3. Propeller diameter
4. Blade activity factor
5. Blade integrated lift coefficient

Of these five, the first is a discrete variable, while the other four are



continuous variables. In other words, there can be only an integer number of blades, but the other variables may take on fractional values.

Discrete variables present a problem for numerical optimization routines. There are two widely used methods of treating this problem. Probably the most obvious method is to search for a local optimum with each possible value of the discrete variable, separately, finally choosing that value for which the best local optimum is found. The second is to treat the discrete variable as a continuous variable, allowing it to have fractional values, and then rounding off to the nearest integer value.

Both methods have advantages and disadvantages. The first approach would obviously be very time consuming if the discrete variable had many possible values. However, it would eventually find the correct optimum. The second method would be faster, but the rounding off procedure could easily be fooled. In practice, with a large range of possible values for the discrete variable, a combination of the two methods may be used. The continuous variable approach could be employed to narrow the choice to a few values of the variable, each of which could then be searched separately.

In the propeller optimization problem, data were available only for 2, 3, and 4-blade propellers, so there are only three possible values of the discrete variable. The individual search approach was therefore employed in the Optimization Routine. Figure 7 outlines this procedure. Unless the number of blades is specified by the operator, the routine first conducts a search with a 4-blade propeller, followed by a 3-blade search. If the 3-blade optimum is worse than the 4-blade optimum, the





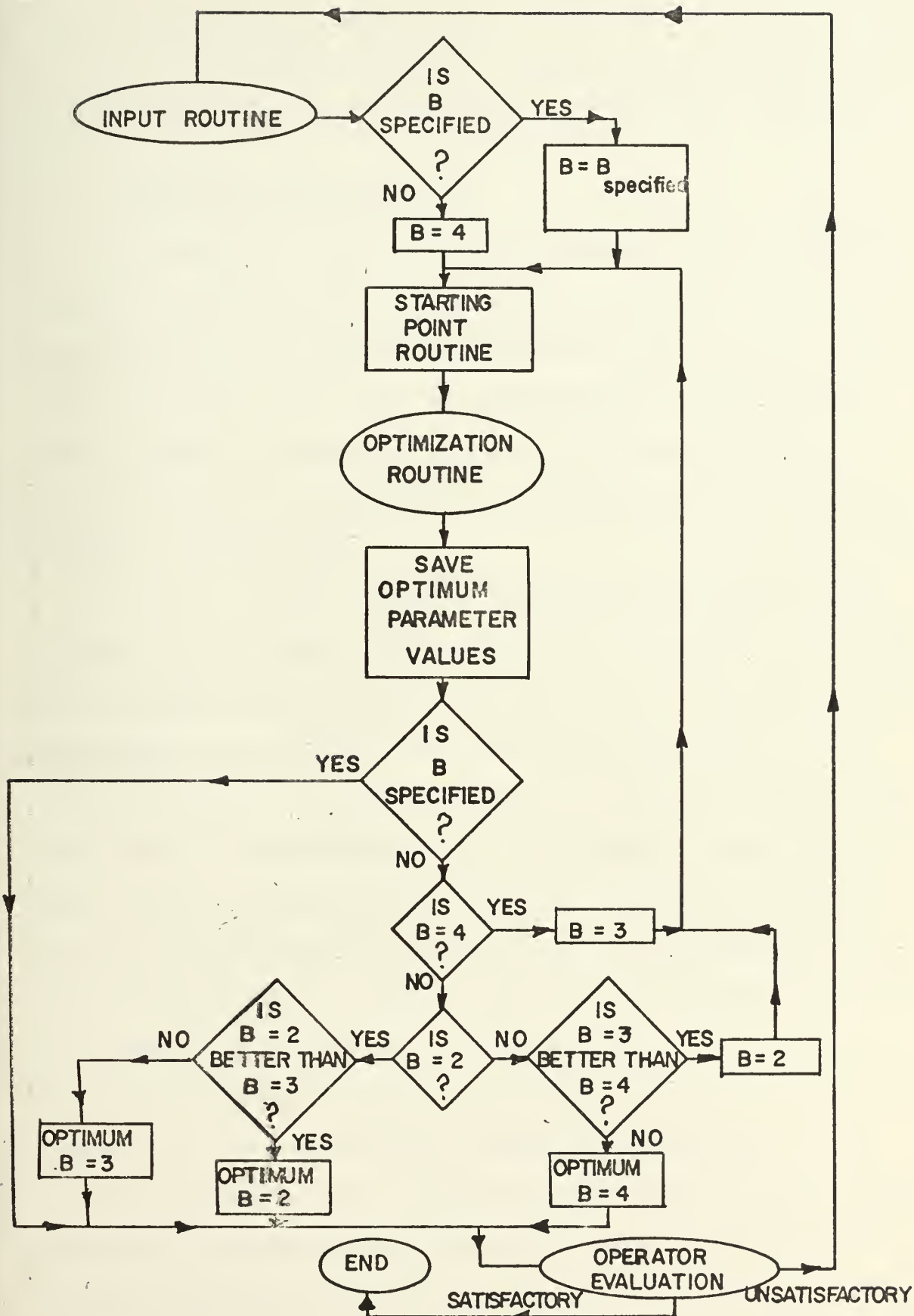


FIGURE 7  
SEARCH PROCEDURE FOR NUMBER OF BLADES



search procedure ends, assuming that a 2-blade propeller would result in a still more inferior performance. However, should the 3-blade propeller outperform the 4-blade prop, then a 2-blade search is conducted.

#### D. PERFORMANCE EVALUATION ROUTINE

The purpose of the Performance Evaluation Routine is to calculate aircraft performance for a given propeller configuration. This is accomplished by use of propeller performance maps found in Ref. 7. These charts give static thrust data and efficiency data for propellers of varying number of blades, activity factor, and integrated lift coefficient. These charts were reduced to data points and are fed into the program on punched cards.

According to Hamilton Standard Division of United Aircraft, the authors of Ref. 7, these data were derived semi-empirically: partially by wind tunnel data and partially by computer computation using a modified vortex theory originally developed by Goldstein in 1929. The technique employed by the PROPOP routine is to reproduce these performance charts by Lagrangian non-linear interpolation of second order. It was found that when each efficiency map was reduced to 42 data points, the accuracy with which this technique could reproduce the full chart was normally within 1%. This was considered quite adequate, as the data are assumed only to be accurate to within 1 - 2%.

Another approach to this calculation might have been to start with vortex theory and let the computer compute the efficiencies just as Hamilton Standard has done. In this way the program would not have been limited to the range of data presented in the charts. However, since data were already available covering a rather substantial range, the



added complexity of the program and the additional computer time which would be required to recalculate this information were considered too great a burden to endure for the amount of aesthetic satisfaction which might have been obtained.

Corrections for compressibility and nacelle blocking effects are presented in graphical form in supplements to Ref. 7. These charts were reduced to data points in the same manner as the efficiency charts and were incorporated into the PROPOP data bank. The accuracy of these corrections is somewhat less than the accuracy of the original data, but they are useful in determining trends. The general operation of the Evaluation Routine is outlined in Fig. 8.

Turbine engines present a problem when it is necessary to calculate their performance under a wide range of operating conditions. In a program such as this, it was considered important to reduce the amount of data required of the operator to a minimum. It was therefore necessary to make assumptions on the variation of engine performance with power setting, altitude, and velocity. The assumptions made are as follows:

1. Shaft horsepower at a given power setting is assumed to vary linearly with altitude and non-linearly (second-order) with velocity.
2. Jet thrust at a given power setting is assumed to be constant with altitude, and to vary linearly with velocity.
3. Fuel consumption at cruise power and altitude is assumed to vary linearly with velocity.
4. Constant engine RPM and constant gear ratio.
5. Takeoff, maximum speed, and climb rate are calculated at same power setting ("maximum power").
6. Range, endurance, and cruise speed are calculated at "cruise power" setting and cruise conditions.



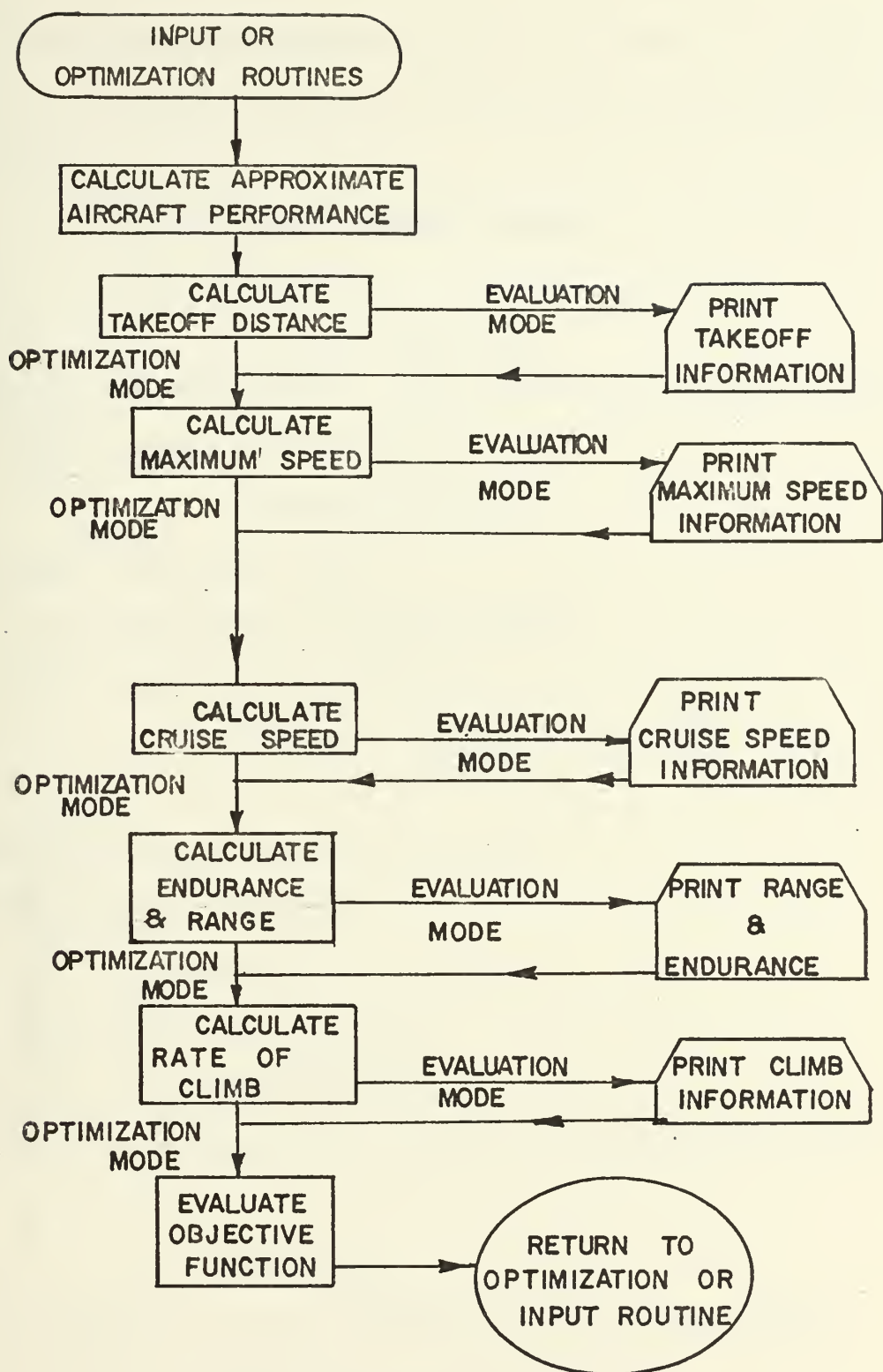


FIGURE 8

## AIRCRAFT PERFORMANCE EVALUATION ROUTINE





With the above assumptions and the data furnished to the program by the operator, engine performance is calculated at all necessary operating conditions.

# 1. Calculation of Takeoff Distance

## a. Assumptions

$$(1) C_D = C_{D_p} + C_{D_i}$$

where:  $C_{D_p}$  = aircraft parasitic drag coefficient in takeoff configuration

$C_{D_i}$  = induced drag coefficient

$$(2) C_{D_i} = C_L^2 / \pi AR e$$

where:  $AR$  = wing aspect ratio

$e$  = wing planform efficiency factor

$C_L$  = aircraft lift coefficient

$$(3) \text{Thrust} = T_{STAT} + [T_{LO} - T_{STAT}] \frac{V^2}{V_{LO}^2} = T_{STAT} + B V^2$$

where:  $T_{STAT}$  = static thrust (zero velocity)

$T_{LO}$  = thrust at liftoff

$V$  = instantaneous velocity (TAS)

$V_{LO}$  = liftoff velocity (TAS)

$$B = [T_{LO} - T_{STAT}] / V_{LO}^2$$

Thrust is assumed to vary parabolically with velocity during takeoff run.

## b. Calculations

acceleration =  $a = F/M$  = summation of forces/aircraft mass

$F$  = thrust - friction drag - aerodynamic drag

$$\text{Drag} = D = \mu [W - L] + \frac{1}{2} \rho V^2 S \left[ C_{D_p} + \frac{C_L^2}{\pi AR e} \right]$$

where:  $\mu$  = coefficient of friction between runway and wheels



$W$  = takeoff weight of aircraft

$L$  = aircraft lift

$\rho$  = air density

$S$  = aircraft wing area

$$\text{or: } D = \mu \left[ W - \frac{1}{2} \rho V^2 S C_L \right] + \frac{1}{2} \rho V^2 S \left[ C_{D_p} + \frac{C_L^2}{\pi A R e} \right]$$

In order to find the optimum  $C_L$  for minimum drag:

$$\frac{dD}{dC_L} = -\frac{1}{2} \mu \rho V^2 S + \frac{\rho V^2 S}{\pi A R e} C_{L_{opt}} = 0$$

$$C_{L_{opt}} = \frac{1}{2} \mu \pi A R e$$

Aircraft is assumed to maintain a constant  $C_L$  ( $C_{L_{opt}}$ ) during takeoff run.

$$a = \frac{g}{W} \left\{ T_{STAT} + B V^2 - \mu \left[ W - \frac{1}{2} \rho V^2 S C_{L_{opt}} \right] - \frac{1}{2} \rho V^2 S C_{D_p} \right\}$$

$$\text{or: } a = \frac{g}{W} \left\{ (T_{STAT} - \mu W) + \left[ B + \frac{1}{2} \rho S (\mu C_{L_{opt}} - C_{D_p}) \right] V^2 \right\}$$

Takeoff distance ( $X_{to}$ ):

$$x_{to} = \int_0^{t_{Lo}} V dt = \int_0^{t_{Lo}} V \frac{dt}{dV} dV = \int_0^{V_{Lo}} \frac{V}{a} dV$$
$$x_{to} = \frac{W}{g} \int_0^{V_{Lo}} \frac{V dV}{A + Z V^2}$$

where:  $A = T_{STAT} - \mu W$

$$Z = (T_{Lo} - T_{STAT}) \frac{1}{V_{Lo}^2} + \frac{1}{2} \sigma \rho_{SL} S (\mu C_{L_{opt}} - C_{D_p})$$

$\rho_{SL}$  = air density at sea level

$$\sigma = \rho / \rho_{SL}$$



so:

$$x_{to} = \frac{W}{2gZ} \ln \left[ V^2 + \frac{A}{Z} \right]_0^{V_{Lo}} = \frac{W}{2gZ} \ln \left[ \frac{V_{Lo}^2 + A/Z}{A/Z} \right]$$

Further assumptions:

- (1)  $\mu = .025$
- (2) no wind
- (3) no runway slope
- (4) standard temperature
- (5)  $\sigma = \exp (-\text{altitude}/28900)$

This procedure is explained in greater detail in Ref. 8.

Takeoff distance can vary greatly with pilot technique, temperature, etc., but this is of little concern to the optimization of a propeller. In general, a good takeoff propeller under the assumed conditions would also be a relatively good takeoff propeller under other conditions. Relative performance of one propeller configuration to another is the important factor.

## 2. Calculation of Endurance and Range

### a. Endurance

Endurance is calculated at cruise speed, cruise power and altitude on the basis of a 45 minute reserve.

Endurance = (fuel capacity/fuel consumption)-45 minutes.

Fuel consumption is assumed constant.

### b. Range

Range is also calculated at cruise speed, cruise power and altitude on the basis of a 45 minute reserve.

Range = Endurance  $\times$   $V_{ave}$



where:  $V_{ave}$  = average velocity during flight or

$$\Delta V = V_{cr} + \frac{1}{2} \Delta V$$

$\Delta V$  = cruise velocity with empty fuel tanks minus cruise velocity with full fuel ( $V_{cr}$ )

$\Delta V$  is estimated as follows:

$$HP_{AVAIL} = \frac{TV}{550} = \frac{DV}{550} \rightarrow V = \frac{HP_{AVAIL}}{D} \cdot 550$$

where:

$$D = \left[ C_{Dp} + \frac{C_L^2}{\pi ARE} \right] \frac{1}{2} \rho V^2 S$$

and

$$C_L = \frac{2W}{\rho V^2 S}$$

$$\therefore V = \frac{550 HP_{AVAIL}}{\frac{1}{2} \rho V^2 S} \left[ \frac{1}{C_{Dp} + \frac{4W^2}{\rho^2 V^4 S^2 \pi ARE}} \right]$$

or

$$(\rho^2 S^2 \pi ARE C_{Dp}) V^4 - 1100 HP_{AVAIL} \rho S \pi ARE V + 4W^2 = 0$$

Taking the derivative with respect to  $W$  :

$$dV = \frac{2W}{\rho S \pi ARE} \left[ \frac{dW}{275 HP_{AVAIL} - \rho S C_{Dp} V^3} \right]$$

or approximately

$$\Delta V = \frac{2W}{\rho S \pi ARE} \left[ \frac{\Delta W / \Delta t}{275 HP_{AVAIL} - \rho S C_{Dp} V^3} \right] \Delta t$$

where:

$$\Delta V = V_{final} - V_{initial}$$

$\Delta t$  = endurance

$-\Delta W / \Delta t$  = fuel consumption rate

$V$  = cruise velocity ( $V_{cr}$ )





$$W = W_{\text{GROSS}} - \frac{1}{2} W_{\text{FUEL}} = \text{average weight}$$

Accounting for increased velocity due to loss of fuel weight typically increases range by 2-3%.

Range and endurance are calculated at cruise speed and conditions for several reasons. If given conditions were not specified, these performance characteristics would have to be determined by an iterative process of varying the engine power setting to determine the best setting and the corresponding aircraft velocity for best endurance. Such a process, although conceptually straight forward, would require more data than are presently required by the Input Routine. For instance, engine fuel consumption would have to be known throughout the entire range of engine operation. The iteration process would also require extensive computational time. In fact, such a procedure would probably double the time required by the entire Evaluation Routine. These penalties were considered too great to justify the computation.

### 3. Calculation of Maximum Velocity and Cruise Velocity

Calculation of maximum aircraft velocity and cruise velocity are essentially identical and the computational procedure is outlined in Fig. 9. Basically the procedure involves locating the intersection of the power available curve and the power required curve (both vs. velocity) by iterating velocity [Ref. 8].

The symbols in Fig. 9 are as follows:

$\Delta$  - step size or velocity increment

N1, N2 - indicators which serve as cues for the routine to branch in the proper direction at certain points

$HP_R$  - thrust horsepower required for level flight at given conditions



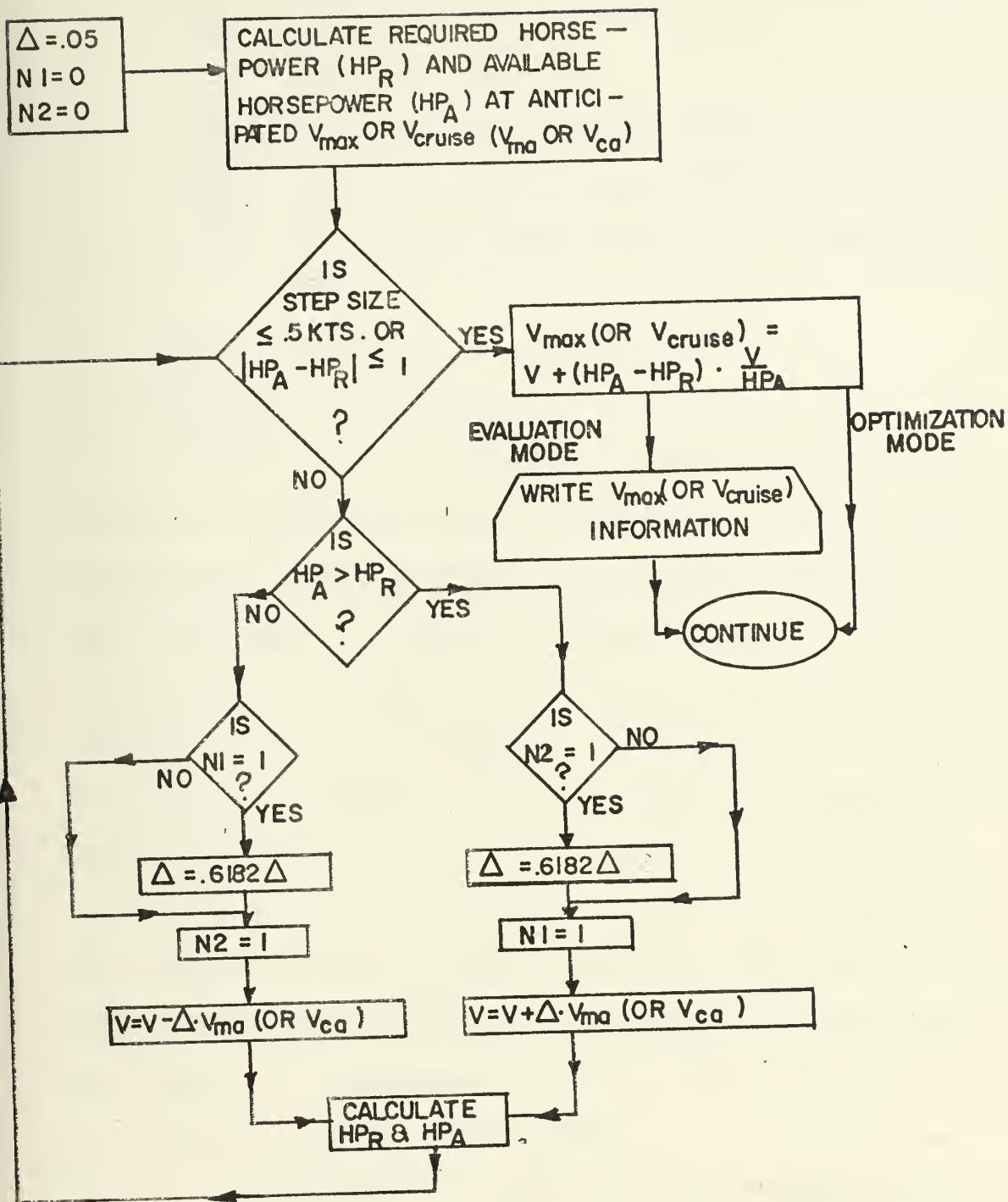


FIGURE 9

CALCULATION OF MAXIMUM VELOCITY AND CRUISE VELOCITY.



velocity step size was set at .5%.of the anticipated climb velocity, so this is the accuracy of the resulting climb velocity. However, at the maximum climb speed, excess thrust horsepower normally varies very slowly, so the accuracy of the actual rate of climb calculation should be much better than .5% given perfect information.

The symbols used in Fig.10 are as follows:

- $\Delta$  - step size (.005 times anticipated climb speed)
- NI - indicator which serves as cue for a switching point in the routine
- V - velocity of aircraft used in calculating excess thrust horsepower (TAS)
- $\Delta HP_1, \Delta HP_2$  - excess thrust horsepower at two consecutive velocity trials
- $HP_R$  - required thrust horsepower for level flight under given conditions
- $HP_A$  - available thrust horsepower at given conditions
- $W_{gross}$  - aircraft gross weight
- R. C. - rate of climb (fpm)



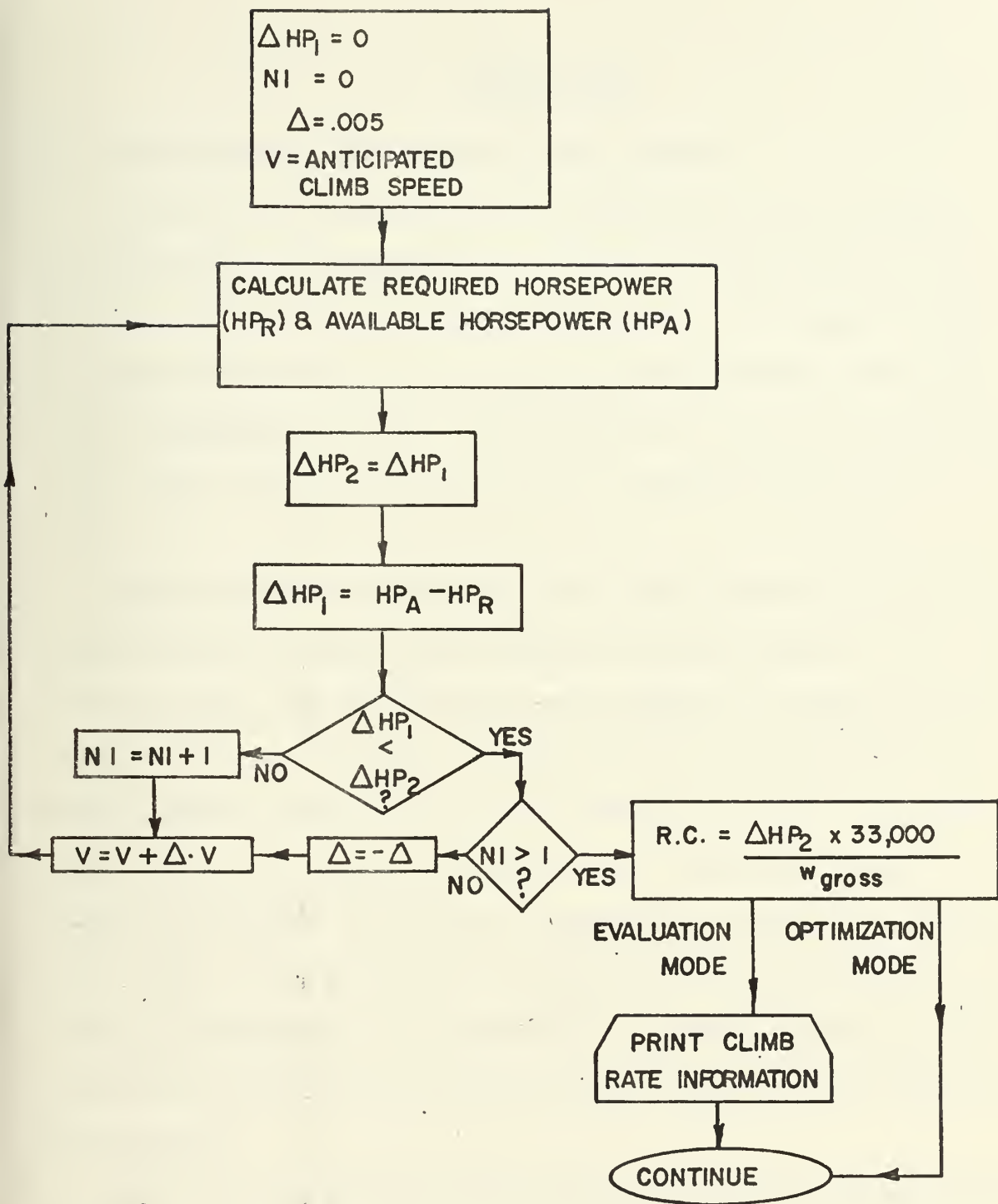


FIGURE 10  
CALCULATION OF CLIMB RATE





### III. PROGRAM USAGE

#### A. OPTIMIZATION OF PROPELLERS FOR GIVEN AIRCRAFT

The first step in optimization of a propeller by use of PROPOP is the gathering of the required data, as listed in Section II B, on the aircraft, engines, and operational requirements. It is important that all engine horsepower (and jet thrust, if turbine powered) information used is installed engine data. Specifications as to operating conditions of the engine must be followed exactly or erroneous calculations will result.

One of the features of PROPOP is that the horsepower limit specified by the operator is automatically imposed on turbine engines. It is therefore unnecessary (and undesirable) for the operator to impose this limit on the horsepower data typed into the program (see Section II B.2.c.). PROPOP recreates engine power curves by fitting given data points with either second order curves or straight lines. These curves could be drastically altered if the operator imposed such artificial constraints on the data. It may be necessary, therefore, to extrapolate engine power curves into regions where the engines do not actually operate in order to provide the program with smoothly varying curves by which trends may be calculated.

Steps 1, 2, and 3 of the Input Routine are required for operation of PROPOP in the optimization mode. Step 4 (Aircraft Performance Constraints) may be omitted altogether. In such a case no constraints are imposed on the aircraft performance. Should the operator desire to specify some, but not all the performance constraints, he may indicate those to be left unspecified by assigning the value zero (0.) to those constraints.



Step 5 (Propeller Constraints) is required, however any constraint, except "maximum blade diameter," may be left unspecified by assigning a value of zero (0.) to that constraint. The range of data acceptable for this step is given in Section II B.5.

Step 6 (Optimization Criteria) is required in the optimization mode. In this step the operator specifies the aircraft performance characteristics for which he requires an optimum propeller. He may specify one or more of these characteristics (Section II B.6) by assigning "values of importance" from zero to ten. The highest values of importance receive the highest priority in the Optimization Routine. It has been found that the best technique for assigning these values of importance is to specify only one, giving zero (0.) as the value of the others. An attempt has been made to insure that the resulting aircraft performance closely reflects the relative values of importance assigned by the operator (in the case of several specified values of importance), however this is not always the case. The operator should specify only one characteristic, such as cruise performance, for the first trial. If the resulting propeller configuration gives other performance characteristics which the operator considers undesirable (such as large takeoff distance), then he may return to the Input Routine (Step 4) and specify a maximum allowable take-off distance or other constraint.

After much testing of PROPOP it was found that most of the objective functions which must be optimized exhibit a "broad bottom" phenomenon. This means that in the region of the desired minimum fairly large changes in the variables may result in very small changes in the function being optimized. As a result of this situation there are many combinations of propeller configuration variables which yield nearly the same value for



Step 5 (Propeller Constraints) is required, however any constraint, except "maximum blade diameter," may be left unspecified by assigning a value of zero (0.) to that constraint. The range of data acceptable for this step is given in Section II B.5.

Step 6 (Optimization Criteria) is required in the optimization mode. In this step the operator specifies the aircraft performance characteristics for which he requires an optimum propeller. He may specify one or more of these characteristics (Section II B.6) by assigning "values of importance" from zero to ten. The highest values of importance receive the highest priority in the Optimization Routine. It has been found that the best technique for assigning these values of importance is to specify only one, giving zero (0.) as the value of the others. An attempt has been made to insure that the resulting aircraft performance closely reflects the relative values of importance assigned by the operator (in the case of several specified values of importance), however this is not always the case. The operator should specify only one characteristic, such as cruise performance, for the first trial. If the resulting propeller configuration gives other performance characteristics which the operator considers undesirable (such as large takeoff distance), then he may return to the Input Routine (Step 4) and specify a maximum allowable takeoff distance or other constraint.

After much testing of PROPOP it was found that most of the objective functions which must be optimized exhibit a "broad bottom" phenomenon. This means that in the region of the desired minimum fairly large changes in the variables may result in very small changes in the function being optimized. As a result of this situation there are many combinations of propeller configuration variables which yield nearly the same value for





a particular aircraft performance characteristic. However the performance characteristics not considered in the optimization may vary greatly with each configuration. For example, two different combinations of gear ratio, diameter, and activity factor may yield the same optimum cruise speed, but takeoff distance for one combination of these variables may be twice that for the other configuration.

Due to "noise" in the data, this broad bottom phenomenon may cause problems of apparent multimodality, or multiple optima. The operator may be surprised and somewhat disillusioned if he optimizes twice for the same performance characteristic and PROPOP gives two very different propeller configurations. However it should make no difference which configuration the operator chooses, since they both provide the same performance. This problem may be greatly reduced by specifying constraints on several performance characteristics, as mentioned above, while optimizing for a single characteristic.

The PROPOP output permits the operator to follow the program's progress through the optimization procedure. After completing the search for a particular number of blades, PROPOP gives the number of function evaluations performed. This is the number of trial solutions attempted in the search. Five hundred (500) solutions are the maximum permitted. If 500 function evaluations are performed, PROPOP gives zero (0.) for the value of this number. This is an indication to the operator that an optimum solution has not been reached, and if more accuracy is desired the limiting number of evaluations must be raised above 500. This may be done simply by changing the next to last calling argument in the "CALL DIRECT" statement, which is statement number 15, near the end of the





INPUT SUBROUTINE (Appendix A). However, such a problem is highly unlikely, as the use of more than 200 evaluations is a very rare occurrence. More information on the optimization subroutine (DIRECT) may be found in the comments preceeding that subroutine (Appendix A).

For the direct search optimization procedure (Section II C.), best results were found by starting with a rather large step size and decreasing it slowly until the desired accuracy was obtained. Consequently, the beginning normalized step size (DELCAP) was set at .816. The step length is decreased to one fourth of its current value ( $\text{RHO} = .25$ ) whenever finer resolution is required. The minimum step size used is .0127. This value has proven to be sufficiently small, and further reduction rarely changes the results of the search. However, should the operator so desire, any of the above values may be changed by consulting the comment section of SUBROUTINE DIRECT and then altering the calling arguments in the "CALL DIRECT" statement previously mentioned. DELCAP is changed by altering statement 8 in SUBROUTINE INPUT. The current values of these arguments are printed in the PROPOP output before each search.

DIRECT operates by assigning the same step size to all variables. This is obviously a disadvantage when the variables have vastly different ranges, such as zero to infinity, and .15 to .7. Consequently, it was arranged that DIRECT would deal only with normalized variables rather than the actual ones. The actual variable values are therefore divided by an assigned step size before being used by DIRECT. The step sizes assigned are as follows:

diameter.....1 ft. (actual value of variable)

gear ratio..... .5 (CSTG)



activity factor ... 90 (CSTA)

integrated  $C_L$  ..... .1 (CSTI)

So the beginning step size for activity factor, for example, is 73.4 (or  $.816 \times 90$ ). In selecting these step sizes, an attempt was made to have the contours of the objective function be as nearly circular as possible near the optimum. In other words a change of one step size in any of the variables should have approximately the same effect on the propeller performance. Such a condition makes optimization more efficient. These step sizes, except that for diameter, may be altered by the operator by changing the values of CSTG, CSTA, or CSTI which are found near the beginning of PROPOP (Appendix A).

Much effort has been placed on restraining the optimization search to the limits of the data available to PROPOP. This is a relatively simple task for variables such as activity factor and integrated lift coefficient because of the well defined limits to these variables in the data. It is very much more difficult, however, for power coefficient ( $C_p$ ) and advance ratio (J). The difficulties arise for several reasons. Power coefficient, for example, has no well defined limits in the data; the limits being different for each chart in Ref. 7. Another problem is that the search procedure does not actually fix  $C_p$  or J. Instead it sets other propeller parameters and later calculates  $C_p$  and J while determining aircraft performance. By that time errors may already have occurred. Because of these complexities, no attempt was made to constrain  $C_p$ . Advance ratio, J, is constrained rather crudely to an upper limit of three (3). The value of J is computed ( $V/ND$ ) assuming a velocity which is the anticipated maximum velocity specified by the operator. If this value is greater than three, PROPOP alters either gear



ratio, to change propeller RPM ( $N$ ), or diameter ( $D$ ), so that  $J$  equals three. If the actual maximum velocity is greater than that assumed by the operator, however,  $J$  will still lie outside the available data. A small overshoot in  $C_p$  or  $J$  is usually not fatal, as the extrapolation employed by PROPOP is usually fairly accurate close to the data limits. Large overshoots, however, can be disastrous, yielding highly inaccurate results (possibly efficiencies less than zero or greater than 100%).

If the value of  $J$  corresponding to maximum speed should be very close to three after an optimization, there is a good possibility that the propeller diameter or gear ratio have been altered during the procedure to restrain the search to the data limits. In this situation it is sometimes possible to obtain a better optimum by increasing the assumed maximum speed (and changing the appropriate corresponding engine data) at the risk of overshooting the bounds of the data.

Due to the process employed in imposing limits on propeller diameter, activity factor and integrated  $C_L$ , PROPOP occasionally gives an optimum propeller with one or more of the parameters very close (well within one initial step size) to its limiting value. In such a case, a slightly better optimum may sometimes be found by constraining that parameter to its limiting value. The operator should not be too surprised, however, if the results of this maneuver yield a propeller with the other variables radically changed from those of the first "optimum" propeller due to the multimodal phenomenon discussed previously in this section. In any case the aircraft performance should not vary more than one percent.

Output provided by PROPOP includes the following information on aircraft performance with the optimized propeller:



1. Takeoff

- a. Takeoff distance
- b. Static Power Coefficient
- c. Static Thrust Coefficient/Power Coefficient ( $C_T/C_P$ )
- d. Propeller efficiency at liftoff
- e. Blade angle (.75R) at zero velocity
- f. Power coefficient at liftoff (CP)
- g. Advance ratio at liftoff (J)
- h. Effective Mach number at liftoff (M(EFF))
- i. Compressibility correction applied to prop efficiency (FT)
- j. Blocking correction applied to prop efficiency (FB)
- k. Brake/shaft horsepower at liftoff (BHP)
- l. Jet thrust (turbine) (TJET)

2. Maximum Speed

- a. Maximum speed
- b. Blade angle (.75R)
- c. Prop efficiency
- d. Power coefficient (CP)
- e. Advance ratio (J)
- f. Effective Mach number (M(EFF))
- g. Compressibility correction applied to prop efficiency (FT)
- h. Blocking correction applied to prop efficiency (FB)
- i. Brake/shaft horsepower (BHP)
- j. Jet thrust (turbine) (TJET)

3. Cruise

- a. Cruise speed
- b. Same values as b.-j. for maximum speed





- c. Range
- d. Endurance
- 4. Climb
  - a. Maximum rate of climb
  - b. Climb speed
  - c. Same values as b.-j. for maximum speed

Effective Mach number is the aircraft Mach number corrected by a factor involving blade integrated  $C_L$ . Effective Mach number, compressibility corrections (FT), and blocking corrections (FB) are explained in supplements to Ref. 7. Listed values of prop efficiency are for corrections already applied. The blocking corrections are six percent below those given in supplements to Ref. 7 to account for interference and slipstream effects not included in the propeller efficiency data. This additional factor was suggested by Lockheed California Company [Ref. 9]. For takeoff performance, where ground effect is present, this additional blocking factor is omitted and only that factor given in supplements to Ref. 7 is applied.

#### B. EVALUATION OF A GIVEN PROPELLER CONFIGURATION

As explained in Section II B., PROPOP may be operated in the evaluation mode by specifying all blade parameters in Step 5 of the Input Routine. Again, as in the optimization mode, Steps 1, 2, 3, and 5 are required. However, Steps 4 and 6 are omitted.

Output data on aircraft performance is identical with that described in part A of this section for operation in the optimization mode, except of course there is no output corresponding to the optimization procedure itself.



#### IV. EXAMPLE PROBLEM: LOCKHEED P-3C

The Lockheed P-3C aircraft was chosen as the test case for the PROPOP system. Choice of this aircraft was based on its use by the Navy and availability of data on the aircraft and propellers.

##### A. EVALUATION

As nearly as could be determined from information provided by the propeller and aircraft manufacturers, the P-3 propeller was optimized for a low power cruise (about 60% NRP) at an altitude of 15,000 feet, and at a speed of 325 kts. (TAS). It appears, however, that the aircraft will not fly at these conditions at full gross weight (135,000 lbs.). Therefore, a reduced weight of 105,000 pounds was used in calculations of cruise performance. Even at its empty weight of 66,211 pounds, the aircraft will not attain 325 kts. It therefore seems possible that the propellers were designed for conditions at which the aircraft cannot operate.

Data used in the P-3 performance evaluation is given in Table I. PROPOP calculates takeoff distance, maximum speed, and rate of climb at the same power setting ("maximum power"). It was therefore necessary to conduct two evaluations. Takeoff distance was calculated using takeoff power (1970°F T.I.T.), while maximum speed and climb rate were calculated at military power (1920°F T.I.T.). A third evaluation was necessary for cruise speed, range and endurance, inasmuch as a reduced gross weight was employed.

It may be noted in Table I that several of the shaft horsepower figures are considerably above the 4500 SHP gearbox limit. This necessity was discussed in Sections II B.2. and III A.



TABLE I

P-3C DATA SHEETAIRCRAFT DATA:

Gross Weight	135,000 (lbs.) (105,000 for cruise)
Wing Area	1300 (sq. ft.)
Number of Engines	4
Aspect Ratio	7.5
Parasitic Drag Coeff., $C_{Dp}$ (takeoff)	.05 (10 AERO
" " " (cruise)	.0247 15D PYLONS)
Wing Efficiency Factor (e)	.98
Fuel Capacity	59,370 (lbs) (29,370 for cruise)
Liftoff Speed	136 @ (kts. TAS) 121 @ 105,000 lbs.

ENGINE DATA:

Engine RPM	13,820	
SHP (assumed cruise power, altitude, and speed)	1755	} 1450°F T.I.T. @ 25°C
SHP (assumed cruise power, altitude, and speed + 50 kts.)	1861	
SHP (max. power, 10,000 ft. MSL, assumed max. speed)	4453 (T.O. @ 4637)	} 0°C
S.L. SHP (max. pwr., 0 kts.)	4305 (T.O. @ 4527)	
S.L. SHP (" " ,100 kts.)	4486 (T.O. @ 4712)	
S.L. SHP (" " ,400 kts.)	5560 (T.O. @ 5790)	
S.L. Jet Thrust (max. pwr., 0 kts.)	627 (T.O. @ 639) lbs.	} 1450°F T.I.T. @ 25°C
" " " (" " ,100 kts.)	520 (T.O. @ 533) lbs.	
" " " (cruise " , 0 kts.)	462 lbs.	
" " " (" " ,100 kts.)	353 lbs.	
Fuel Flow (assumed cruise power, altitude, and speed)	1035 lbs/hr	
Fuel Flow (assumed cruise power, altitude, and speed + 50 kts.)	1065 lbs/hr	
Limiting SHP	4500 (gearbox limit)	

ENVIRONMENT & ANTICIPATED SPEEDS:

Takeoff Altitude	0	ft. MSL
Climb Altitude	0	" "
Cruise Altitude	15,000	" "
Max. Speed Altitude (assumed)	10,000	" "
Anticipated Climb Speed	235	kts. TAS
" Cruise "	250	" "
" Maximum "	386	" "



Results of this performance evaluation and comparison with available flight test data are presented in Table II. Good correlation was obtained between the predicted and the flight test values. The largest error was obtained in takeoff distance (about 4%). The predicted value may be slightly conservative, but considering the many variables controlled by the pilot during takeoff, this is not thought to be a significant error.

TABLE II  
COMPARISON OF FLIGHT TEST DATA AND PREDICTED  
PERFORMANCE OF P-3C AIRCRAFT

<u>PERFORMANCE</u>	<u>FLIGHT TEST</u>	<u>PREDICTION</u>
Takeoff Distance	4300 ft.	4459 ft.
Maximum Speed	386 kts.	388 kts.
Cruise Speed	*	287 kts.
Range	*	1742 n. mi.
Endurance	*	5.9 hrs.
Rate of Climb	2010 fpm.	2086 fpm.

\*Flight test data not available for chosen conditions.

#### B. OPTIMIZATION OF P-3 PROPELLER

As an example, the P-3 propeller was optimized for the low power cruise discussed in part A of this section. It was assumed that the gear ratio (13.54:1) was determined by the engine manufacturer and was therefore constrained. The maximum allowable propeller diameter for structural clearance of the P-3C is 13.5 feet. Takeoff distance was constrained to under 2500 feet at a gross weight of 105,000 pounds.





A sample computer printout of the input sequence and the PROPOP output is found in Appendix B. The optimum propeller characteristics may be compared with the P-3 propeller [Ref. 10] in Table III. They vary only slightly, however the performance of the optimum propeller exceeds that predicted for the operational P-3 propeller in every respect. The performance comparison is given in Table IV.

TABLE III  
COMPARISON OF OPERATIONAL P-3C PROPELLER  
AND SAMPLE OPTIMUM PROPELLER

	<u>P-3</u>	<u>OPTIMUM</u>
Number of Blades	4	4
Gear Ratio	13.54:1	13.54:1*
Diameter	13.5 ft.	13.5 ft**
Activity Factor	163	220***
Integrated $C_L$	.286	.321

\*Assumed given  
 \*\*Maximum diameter for structural clearance  
 \*\*\*Upper limit of data available

TABLE IV  
PREDICTED PERFORMANCE COMPARISON BETWEEN  
OPERATIONAL P-3 PROPELLER AND SAMPLE OPTIMUM

<u>PERFORMANCE</u>	<u>P-3</u>	<u>OPTIMUM</u>
Takeoff	4459 ft.	3875 ft.
Maximum speed	388 kts.	389 kts.
Cruise speed	287 kts.	290 kts.
Range	1742 n. mi.	1853 n. mi.*
Endurance	5.9 hrs.	6.2 hrs.*
Climb	2086 fpm.	2202 fpm.

\*Based on 29,370 pounds of fuel. (105,000 pounds gross weight)



## V. EVALUATION OF PROJECT SUCCESS

It is felt that the original objectives as previously stated have been realized successfully. A practical, relatively easy-to-use computer program has been developed for use of empirical data in the process of optimum propeller selection. PROPOP has been shown to predict aircraft performance with acceptable accuracy and to improve on existing hardware design.

Time required from collected data to final propeller selection has been reduced from the sixteen man-hours necessary with a manual system to one half man-hours using PROPOP. A 97% reduction in required time with acceptable accuracy is considered sufficient incentive for further investigation into the feasibility of this system.



## VI. PROBLEMS ENCOUNTERED AND AREAS FOR FUTURE RESEARCH

Several problems were encountered in the development of the PROPOP system which, although apparently solved, may cause future difficulties. One such area is the constraint procedure employed during optimization, especially concerning  $C_p$  and J as discussed in Section III A.

Further improvements could be made in the prediction of turbine engine performance. It appears possible that excessive data are presently required and the resulting predictions are not as accurate as might be hoped. Some simple functional relations for performance versus throttle setting, altitude, and velocity would be highly desirable.

More flexibility and a more sophisticated calculation of range and endurance would also be desirable. At present these characteristics are calculated rather crudely at cruise conditions.

The optimization procedure could also bear much more work. A system by which final aircraft performance relates more closely to assigned "values of importance" would be a significant improvement. The pattern-search algorithm upon which the optimization depends should be more thoroughly investigated to determine if another algorithm might be preferable for the propeller optimization problem.

The "broad bottom" phenomenon observed, which often leads to multiple optima, should be investigated further. The possibility exists of rescaling the variables in an attempt to alleviate this problem. Other approaches might also be considered.

The determination of the optimum relationship between the propeller variables for producing near-circular contours near the optimum is an



area which might be considered. The optimum initial step length and the best rate of reducing this length could also lead to improvements in program efficiency.

If accurate theoretical methods of predicting propeller performance could be substituted for the empirical data and interpolation procedure employed by PROPOP, there exists the possibility of much improvement. Data could be eliminated, accuracy might be improved, and available data limitations could be removed which would eliminate many of the constraint troubles. Such a substitution might even solve the multiple-optima problem.

PROPOP in its present form is really only a beginning, with vast room for improvement. For instance, there seems to be no reason why a similar method could not be developed for optimal design of an entire aircraft.





APPENDIX A  
COMPUTER PROGRAM



```

COMMON STATCP(28,4,8,3),STATCT(28,4,8,3),VJV(7),BETA(4,4,4,5,3),STA
AFLT,WAR,ENG(6,7,4,5,3),FLTP,AR,CDPCR,CDPTO,E,FUELC,RPV,NTYCR,BHPV,
C8HPTO,TJETTO,BHPC,RPVCL,TJETCL,BHPCR,AVCL,AVCR,AVM,TTOCCNT,
DRPMVM,TJETVM,FCNCON,GR,ALTTO,ALTICR,ALTICR,ALTICR,ALTICR,ALTICR,
ECLCON,VOIRA,VOIRA,VOIRA,VOIRA,VOIRA,VOIRA,VOIRA,VOIRA,VOIRA,VOIRA,
FVOICV(4),NAF(3),BETAV(27),CT(5),AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,
HVJV(4),BETAV(27),CT(5),AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,
IJETM1,BETAV(27),CT(5),AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,
JETAVM,BETAV(27),CT(5),AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,
KRETMV(4),BETAV(27),CT(5),AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,AFVCL,
LDEPAV(4,5),STAT/STATCP,STATCT/FLTP,FLTP,FLTP,FLTP,FLTP,FLTP,FLTP,
MNAMELIST/COMPAV,EPAAV,SHPV
1FSUBBV,EPAAV,SHPV
WRITE(6,1098)
FORMAT(4,STAT)
READ(4,FLTP)
READ(4,COMPAV)
WRITE(6,1099)
FORMAT(4,STAT)
RHO=0.002378
G=32.2
CSTI=90.
CSTI=.5
CALL INPUT
1 STOP
END

1098
1099
1

FUNCTION SIGMA(ALT)
SIGMA=EXP(-ALT/28900.)
RETURN
END

SUBROUTINE LIN(X1,X2,Y1,Y2,XZERC,YZERO)
LINEAR INTERPOLATION SUBROUTINE
X1,X2 = VALUES OF INDEPENDENT VARIABLE BRACKETING XZERO
Y1,Y2 = VALUES OF INDEPENDENT VARIABLE CORRESPONDING TO X1,X2
XZERO = INDEPENDENT VARIABLE VALUE OF INTEREST
YZERO = VALUE OF DEPENDENT VARIABLE CORRESPONDING TO XZERO

```

```

PR0000170
PR0000180
PR0000190
PR0000200
PR0000210
PR0000220
PR0000230
PR0000240
PR0000250
PR0000260
PR0000270
PR0000280
PR0000290
PR0000300
PR0000310
PR0000320
PR0000330
PR0000340
PR0000350
PR0000360
PR0000370
PR0000380
PR0000390
PR0000400
PR0000410
PR0000420
PR0000430
PR0000440
PR0000450
PR0000460

```



```

R=(XZERO-X1)/(X2-X1)
YZERO=Y1+R*(Y2-Y1)
RETURN
END

```

```

NON-LINEAR INTERPOLATION (LAGRANGIAN) WITH ARBITRARY TABULAR INTERVAL
SURROUTINE NONLIN(X1,X2,X3,Y1,Y2,Y3,XZERO,YZERO)
      X1,X2,X3 = VALUES OF INDEPENDENT VARIABLE BRACKETING XZERO
      Y1,Y2,Y3 = VALUES OF DEPENDENT VARIABLE CORRESPONDING TO X1,
                  X2,X3
      XZERO = VALUE OF INDEPENDENT VARIABLE FOR WHICH VALUE OF
                  DEPENDENT VARIABLE, YZERO, IS SOUGHT
      YZERO = VALUE OF DEPENDENT VARIABLE AT XZERO

      YZERC=((XZERO-X2)*(XZERC-X3))/((X1-X2)*(X1-X3))*Y1+((XZERO-X1)
1*(XZERC-X3))/((X2-X1)*(X2-X3))*Y2+(((XZERO-X1)*(XZERO-X2))/
2((X3-X1)*(X3-X2)))*Y3
      RETURN
      END

```

[illegible]

FR000920









```

13 CONTINUE
CALL NCNLI(NAFVLT(NAF(1)),AFVLT(NAF(2)),AFVLT(NAF(3)),ETAVP1(1)
1,ETAVP1(2),ETAVP1(3),AF,ETAP)
CL1=CL1/CST1
AF=AF/CSTA
RETURN
END
PR001410
PR001420
PR001430
PR001440
PR001450
PR001460
PR001470

```

```

SUBROUTINE BLDANG(CP,VJS,BETAP)
SUBROUTINE FOR CALCULATING PROPELLER BLADE ANGLE (.75R) AT A GIVEN
ENGINE POWER COEFFICIENT AND GIVEN PROPELLER ADVANCE RATIO
CP = DIMENSIONLESS ENGINE POWER COEFFICIENT (V/ND)
VJS = DIMENSIONLESS PROPELLER ADVANCE RATIO (V/ND)
BETAP = PROPELLER BLADE ANGLE (.75R)
PR001480
PR001490
PR001500
PR001510
PR001520
PR001530
PR001540
PR001550
PR001560
PR001570

```

```

DIMENSION BETAVP(9),BETAV1(3)
COMMON STACP(28,4,8,3),FLTPETA(6,7,4,5,3),FLTCPB(4,4,5,3),NCP(3),CSTA,
AFLTCPPE(6,7,4,8,3),PRCP,AR,CPMCL,TJETTCL,BHPCR,AVM,TOCCONT,
CBWPTQ,RPMTQ,TJETVMT,JECON,GR,ALTTO,ALTMCL,AD,AVM,TOCCONT,
DRPMVM,TJETVMT,JECON,GR,ALTTO,ALTMCL,AD,AVM,TOCCONT,
DECLCON,TJETVMT,JECON,GR,ALTTO,ALTMCL,AD,AVM,TOCCONT,
FVCLCON,TJETVMT,JECON,GR,ALTTO,ALTMCL,AD,AVM,TOCCONT,
GCLIV(4),NATF(3),BETAV(2,7),RPM,TJETC2,FCOR,RANGE,ENDUR,BETAST,
HVJB(4),BETAV(2,7),RPM,TJETC2,FCOR,RANGE,ENDUR,BETAST,
IJETVMT,BETAV(2,7),RPM,TJETC2,FCOR,RANGE,ENDUR,BETAST,
JETACL(4),BETAV(2,7),RPM,TJETC2,FCOR,RANGE,ENDUR,BETAST,
KBECLM(4),BETAV(2,7),RPM,TJETC2,FCOR,RANGE,ENDUR,BETAST,
LDEP(4,5),EPALT(4,5),SHPV(5),NUMBLS,VCRLT,COORD(4,4),COORDF(4)
DO 1 I=1,3
IF(VJS.LT.VJB(1))GO TO 2
IF(VJS.GE.VJB(I)).AND.VJS.LE.VJB(I+1))GO TO 2
CONTINUE
1 2 IF(I.EQ.3)GO TO 3
NJ(1)=I+1
NJ(2)=I+2
GO TO 4
3 NJ(1)=I+1
NJ(2)=I-1
NJ(3)=I-1
I=1,3
4 DO 5 K=1,3
DO 6 K=1,3
DO 7 K=1,3

```

```

PR001750
PR001760
PR001770
PR001780
PR001790
PR001800
PR001810
PR001820
PR001830
PR001840
PR001850
PR001860
PR001870
PR001880

```

CCCCCCCC



[illegible]

```

1 N1=K+3*(J-1)+9*(I-1)
2 DO 8 N=1,3
3 IF(CP.LT.FLTCPB(1,NJ(K),NCLI(J),NAF(I),NB))GO TO 9
4 IF(CP.GE.FLTCPB(N,NJ(K),NCLI(J),NAF(I),NB))GO TO 9
5 1 NJ(K),NCLI(J),NAF(I),NB)GO TO 9
6 1 CONTINUE
7 8 IF(N.EQ.3)GO TO 10
8 9 NCP(1)=N
9 10 NCP(2)=N+1
10 11 NCP(3)=N+2
11 12 GO TO 11
12 13 NCP(1)=N+1
13 14 NCP(2)=N
14 15 NCP(3)=N-1
15 16 CALL NONLIN(FLTCPB(NCP(1),NJ(K),NCLI(J),NAF(I),NB),FLTCPB(NCP(2),NJ(K),NCLI(J),NAF(I),NB),FLTCPB(NCP(3),NJ(K),NCLI(J),NAF(I),NB)),NAF(I),NB),BETA(NCP(1),NJ(K),NCLI(J),NAF(I),NB),BETA(NCP(2),NJ(K),NCLI(J),NAF(I),NB),BETA(NCP(3),NJ(K),NCLI(J),NAF(I),NB),CP,BETAV(N1))
16 17 CONTINUE
17 18 CONTINUE
18 19 CONTINUE
19 20 N=1
20 21 DO 12 I=1,25,3
21 22 CALL NONLIN(VJVB(NJ(1)),VJVB(NJ(2)),VJVB(NJ(3)),BETAV(I+1),BETAV(I),BETAV(I+1),BETAV(I+2)),VJS,BETAV(N)
22 23 1),BETAV(I+2),VJS,BETAV(N)
23 24 N=N+1
24 25 12 CONTINUE
25 26 N=1
26 27 CLF=CLF*CSTI
27 28 AF=AF*CSTA
28 29 DO 13 I=1,7,3
29 30 CALL NONLIN(CLIV(NCLI(1)),CLIV(NCLI(2)),CLIV(NCLI(3)),BETAV(I),BETAV(I+1),BETAV(I+2),BETAV(I+3)),BETAV(I),BETAV(I+1),BETAV(I+2),BETAV(I+3)),AFVFLT(NAF(1)),AFVFLT(NAF(2)),AFVFLT(NAF(3)),BETAV(1),BETAV(2),BETAV(3)),AF,BETAP)
30 31 1,BETAV(1),BETAV(2),BETAV(3),AF,BETAP)
31 32 CLF=CLF/CSTI
32 33 AF=AF/CSTA
33 34 RETURN
34 35 END

```

SUBROUTINE DIRECT  
PURPOSE TO LOCATE A LOCAL MINIMUM OF A FUNCTION: S, OF K VARIABLES  
BY THE METHOD OF DIRECT SEARCH (HOOKE AND JEEVES)

UUUUUUUU



PR002370  
PR002380  
PR002390  
PR002400  
PR002410  
PR002420  
PR002430  
PR002440  
PR002450  
PR002460  
PR002470  
PR002480  
PR002490  
PR002500  
PR002510  
PR002520  
PR002530  
PR002540  
PR002550  
PR002560  
PR002570  
PR002580  
PR002590  
PR002600  
PR002610  
PR002620  
PR002630  
PR002640  
PR002650  
PR002660  
PR002670  
PR002680  
PR002690  
PR002700  
PR002710  
PR002720  
PR002730  
PR002740  
PR002750  
PR002760  
PR002770  
PR002780  
PR002790  
PR002800  
PR002810  
PR002820  
PR002830  
PR002840

USAGE CALL DIRECT(PSI,K,SPSI,DELCAP,RHO,DELLC,S,KONVRG,MAXEV,KN)

DESCRIPTION OF PARAMETERS  
PSI - VECTOR OF K INDEPENDENT VARIABLES. IT IS FILLED INITIALLY BY USER WITH FIRST ESTIMATE OF SOLUTION. AT EXIT FROM DIRECT IT CONTAINS BEST VALUES ATTAINED.  
K - NUMBER OF INDEPENDENT VARIABLES OF FUNCTION, S, TO BE MINIMIZED  
SPSI - AT EXIT FROM DIRECT CONTAINS SMALLEST S(PSI) ATTAINED  
DELCAP - INITIAL STEP LENGTH (SAME FOR ALL VARIABLES)  
N.B. DELCAP IS ALTERED BY DIRECT. DO NOT USE NUMERICAL VALUE IN CALLING LIST.  
RHO - REDUCTION FACTOR (0.LT.RHO.LT.1). THE VALUE .125 OR .25 IS SUGGESTED  
DELLC - END CRITERION. WHEN CURRENT STEP SIZE IS LESS THAN DELLC, THE SEARCH IS TERMINATED.  
S - THE NAME OF AN EXTERNAL FUNCTION, S(PHI), TO BE MINIMIZED. A FUNCTION SUBPROGRAM OF THE NAME MUST BE SUPPLIED BY THE USER.  
KONVRG - AN INDICATOR TO BE TESTED BY USER UPON EXIT FROM DIRECT. IF KONVRG ERROR WAS DETECTED, FOR EXAMPLE =-1, A PARAMETER K.LE.0,  
DELCAP.LE.0, OR RHO.GE.1, MADE IMMEDIATELY.)  
DELLC.LE.0, (RETURN IS NOT MINIMUM.)  
=0, MAXEV.WAS EXCEEDED. (SPSI IS NOT MINIMUM.)  
MAXEV - .GT.0, IN SPSP = (SUCCESS IS INDICATED.) USER WILL ALLOW FUNCTION EVALUATIONS IF MAXEV.LE.0, AN EFFECTIVE VALUE OF 500 WILL BE USED TO OBTAIN DIAGNOSTIC OUTPUT IF PR002710  
KN - AN INDIARY. IF KN OF FUNCTION VALUE AND CORRESPONDING VARIABLES IS MADE AT THE ORIGIN, AFTER EACH EXPLORE MOVE, OR AFTER EACH AT EXIT, WITH FINAL VALUE OF KONVRG. OUTPUT IS ACCOMPLISHED BY DIRECT.  
=0, NO OUTPUT IS MADE AS IN THE CASE KN.LE.-1, EXCEPT  
KN - .GT.1, OUTPUT MOVES ARE OMITTED.  
NOTE. EXPLORE CASES KN.NE.0, OUTPUT OF PARAMETERS IS ALSO MADE BEFORE SEARCH REGINS. ALL OUTPUT IS ON MEDIUM 6.

METHOD











```

60 SLC(I) = DELCAP
   IF((PSI(1)/PSI(2)).GT.((3.*RPMVM)/(101.4*AVM*CS TG)).AND.GRS.EQ.0.)
   1 PSI(1)=(3.*PSI(2)*RPMVM)/(101.4*AVM*CS TG)
   1 IF((PSI(1)/PSI(2)).GT.((3.*RPMVM)/(101.4*AVM*CS TG)).AND.DS.EQ.0.
   1 AND.GRS.NE.0.)PSI(2)=(PSI(1)*101.4*AVM*CS TG)/(3.*RPMVM)
   1 IF(PSI(2).GT.DMAX)PSI(2)=DMAX
   SPSI = S(PSI)
   EVAL = 1
C
61 WRITE(6,1)MRL
208 FORTEAT(6,63)BEGIN,12,' BLADE SEARCH',
63 FORMAT(//14H1DIRECT SEARCH,2X,8HDELCAP =,E15.6,2X,5HRHO =,E15.6,
12X,7HDELCAP =,E15.6,2X,8HMAXEVL =,I8,2X,5HKN =,I3//8HMOVE ,
215HFUNCTION,VALUE,4X,'GEAR RATIO',8X,'PROP DIAM.',5X,
3 ACTIVITY,FAC,4X,'INTEG. LIFT COEFF.')
```



```

PR0003810
PR0003820
PR0003830
PR0003840
PR0003850
PR0003860
PR0003870
PR0003880
PR0003890
PR0003900
PR0003910
PR0003920
PR0003930
PR0003940
PR0003950
PR0003960
PR0003970
PR0003980
PR0003990
PR0004000
PR0004010
PR0004020
PR0004030
PR0004040
PR0004050
PR0004060
PR0004070
PR0004080
PR0004090
PR0004100
PR0004110
PR0004120
PR0004130
PR0004140
PR0004150
PR0004160
PR0004170
PR0004180
PR0004190
PR0004200
PR0004210
PR0004220
PR0004230
PR0004240
PR0004250
PR0004260
PR0004270
PR0004280

IF(I.EQ.3.AND.AFS.NE.0.)GO TO 20
IF(I.EQ.4.AND.CLIS.NE.0.)GO TO 20
IF(SLC(I)) 21,50,22
IF(PHI(I)).GT.PSI(I) SLC(I) =-SLC(I)
21 GO TO 23
IF(PHI(I)).LT.PSI(I) SLC(I) = -SLC(I)
22
23 THET = PSI(I)
PSI(I) = PHI(I)
PSI(I) = 2.*PHI(I) - THET
IF((PHI(3)).GT.(220./CSTA)).OR.(NUMBL.EQ.2.AND.PHI(3).GT.(120./CSTA
1))GO TO 56
1 GO TO 57
IF(NUMBL.EQ.2)PHI(3)=120./CSTA
56 IF(NUMBL.NE.2)PHI(3)=220./CSTA
IF(PHI(3)).LT.(80./CSTA)PHI(3)=80./CSTA
57 IF(PHI(4)).GT.(7./CSTI)PHI(4)=.7/CSTI
IF((PHI(4)).LT.(.15/CSTI)).OR.(NUMBL.EQ.2.AND.PHI(4).LT.(.3/CSTI))
1 GO TO 58
1 GO TO 59
IF(NUMBL.EQ.2)PHI(4)=.3/CSTI
58 IF(NUMBL.NE.2)PHI(4)=.15/CSTI
IF((PHI(1))/PHI(2)).GT.((3.*RPMVM)/(101.4*AVM*CSTG)).AND.GRS.EQ.0.)
59 IF((PHI(1))/PHI(2))*RPMVM/(101.4*AVM*CSTG)
1PHI(1)=(3.*PHI(2))*RPMVM/(101.4*AVM*CSTG)
IF((PHI(1))/PHI(2)).GT.((3.*RPMVM)/(101.4*AVM*CSTG)).AND.DS.EQ.0.
1 AND.GRS.NE.0.)PHI(2)=(PHI(1)*101.4*AVM*CSTG)/(3.*RPMVM)
1 IF(PHI(2)).GT.DMAX.AND.DS.EQ.0.)PHI(2)=DMAX
20 CONTINUE

C
SPSI = SS
SPHI=S(PHI)
SS=SPHI
EVAL = EVAL +1
ASSIGN 25 TO IBK

C
DO 41 I=1,K
IF(I.EQ.1.AND.GRS.NE.0.)GO TO 41
IF(I.EQ.2.AND.DS.NE.0.)GO TO 41
IF(I.EQ.3.AND.AFS.NE.0.)GO TO 41
IF(I.EQ.4.AND.CLIS.NE.0.)GO TO 41
THET = PHI(I)
SLCI = SLC(I)
PHI(I) = THET+SLCI
IF((PHI(3)).GT.(220./CSTA)).OR.(NUMBL.EQ.2.AND.PHI(3).GT.(120./CSTA
1))GO TO 7C
1 GO TO 71
IF(NUMBL.EQ.2)PHI(3)=120./CSTA
70 IF(NUMBL.NE.2)PHI(3)=220./CSTA
71 IF(PHI(3)).LT.(80./CSTA)PHI(3)=80./CSTA

```



```

PR004290
PR004300
PR004310
PR004320
PR004330
PR004340
PR004350
PR004360
PR004370
PR004380
PR004390
PR004400
PR004410
PR004420
PR004430
PR004440
PR004450
PR004460
PR004470
PR004480
PR004490
PR004500
PR004510
PR004520
PR004530
PR004540
PR004550
PR004560
PR004570
PR004580
PR004590
PR004600
PR004610
PR004620
PR004630
PR004640
PR004650
PR004660
PR004670
PR004680
PR004690
PR004700
PR004710
PR004720
PR004730
PR004740
PR004750
PR004760
IF(PHI(4).GT.(.7/CSTI))PHI(4)=.7/CSTI
IF((PHI(4).LT.(.15/CSTI)).OR.(NUMBL.EQ.2.AND.PHI(4).LT.(.3/CSTI)))
1GO TO 72
1GO TO 73
72 IF(NUMBL.EQ.2)PHI(4)=.3/CSTI
IF(NUMBL.NE.2)PHI(4)=.15/CSTI
IF((PHI(1)/PHI(2)).GT.((3.*RPMVM)/(101.4*AVM*CSSTG)).AND.GRS.EQ.0.)
73 IF((PHI(1)/PHI(2)).*RPMVM)/(101.4*AVM*CSSTG)
1PHI(1)=(3.*PHI(2)).*RPMVM)/(101.4*AVM*CSSTG)).AND.DS.EQ.0.
1IF((PHI(1)/PHI(2)).GT.((3.*RPMVM)/(101.4*AVM*CSSTG)/(3.*RPMVM)
1AND.GRS.NE.0.)PHI(2)=(PHI(1)*101.4*AVM*CSSTG)/(3.*RPMVM)
1IF(PHI(2).GT.DMAX.AND.DS.EQ.0.)PHI(2)=DMAX
SPHI=S(PHI)
EVAL=EVAL+1
IF(SS=GT.SPHI)GO TO 42
IF((I)=THET-SLCI
PHI(1)=PHI(3).GT.(220./CSTA)).OR.(NUMBL.EQ.2.AND.PHI(3).GT.(120./CSTA
1))GO TO 75
1GO TO 76
75 IF(NUMBL.EQ.2)PHI(3)=120./CSTA
IF(NUMBL.NE.2)PHI(3)=220./CSTA
76 IF((PHI(3).LT.(80./CSTA))PHI(3)=80./CSTA
IF(PHI(4).GT.(.7/CSTI))PHI(4)=.7/CSTI
IF((PHI(4).LT.(.15/CSTI)).OR.(NUMBL.EQ.2.AND.PHI(4).LT.(.3/CSTI)))
1GO TO 77
1GO TO 78
77 IF(NUMBL.EQ.2)PHI(4)=.3/CSTI
IF(NUMBL.NE.2)PHI(4)=.15/CSTI
78 IF((PHI(1)/PHI(2)).GT.((3.*RPMVM)/(101.4*AVM*CSSTG)).AND.GRS.EQ.0.)
1PHI(1)=(3.*PHI(2)).*RPMVM)/(101.4*AVM*CSSTG)
1IF((PHI(1)/PHI(2)).GT.((3.*RPMVM)/(101.4*AVM*CSSTG)).AND.DS.EQ.0.
1AND.GRS.NE.0.)PHI(2)=(PHI(1)*101.4*AVM*CSSTG)/(3.*RPMVM)
1IF(PHI(2).GT.DMAX.AND.DS.EQ.0.)PHI(2)=DMAX
SPHI=S(PHI)
EVAL=EVAL+1
IF(SS=I*GE.SS)GO TO 44
IF(SPHI=-SLCI
SLC(I)=-SLCI
42 SS=SPHI
44 GO TO 41
41 PH(I)=THET
CONTINUE
GO TO IBK,(11,25)
C
C
25 IF(KN) 27,28,29*CSSTG
27 PH(I)=PHI(1)*CSSTG
28 PH(I)=PHI(3)*CSSTG
29 PH(I)=PHI(4)*CSSTG
WRITE( 6,29) SS,(PHI(I),I=1,K)

```



PR004770  
PR004780  
PR004790  
PR004800  
PR004810  
PR004820  
PR004830  
PR004840  
PR004850  
PR004860  
PR004870  
PR004880  
PR004890  
PR004900  
PR004910  
PR004920  
PR004930  
PR004940  
PR004950  
PR004960  
PR004970  
PR004980  
PR004990  
PR005000  
PR005010  
PR005020  
PR005030  
PR005040  
PR005050  
PR005060  
PR005070

PR005080  
PR005090  
PR005100  
PR005110  
PR005120

25 FORMAT(8H PATTERN,E15.7,8X,F6.2,12X,F6.2,12X,F6.1,14X,F6.3)

PHI(1)=PHI(1)/CSTG  
PHI(3)=PHI(3)/CSTA  
PHI(4)=PHI(4)/CSTI

C 28 IF(SS\*GE\*SPSI) GO TO 1

DO 26 I=1,K  
IF(ABS(PHI(I)-PSI(I)).GT.0.5\*ABS(SLC(I))) GO TO 2  
26 CONTINUE

C 3 IF(DELCAP.LT.DELLC) GO TO 52

DELCAP = RHO \* DELCAP  
DO 30 I=1,K  
SLC(I) = RHO \* SLC(I)  
30 GO TO 1

C 50 KONVRG = -1

GO TO 55

51 KONVRG = 0

52 GO TO 55

SPSI=S(PSI)

EVAL=EVAL+1

KONVRG = EVAL

55 WRITE(6,209)NUMBL,KONVRG

209 FORMAT(/,END OF,I2,' BLADE SEARCH...',I10,' FUNCTION EVALUATIONS

PERFORMED')

53 DO 8C I=1,4

8C COORD(NUMBL,I)=PSI(I)

COORDF(NUMBL)=SPSI

54 RETURN

END

SUBROUTINE COMP(VJ,VKTS,ALT,FSUBT,FSUBR)

SUBROUTINE COMP CALCULATES COMPRESSIBILITY AND BLOCKING

EFFECTS ON PROPELLER PERFORMANCE

COMMON STATCP(28,4,8,3),STATCT(28,4,8,3),VJV(7),BETA(4,4,4,5,3),  
AFLTCP(6,7,4,5,3),FLTEA(6,7,4,5,3),FLTCPB(4,4,4,5,3),NCP(3),CSTA,  
ABWT,WAREA,NUMENG,ITTO,PROP,AR,CCPCR,CDPTQ,E,BHPCR,RPMCR,AVCL,AVCR,AVM,TCCQNT,  
CBHPTQ,RPMTC,TJETVM,FCNCON,GR,ALCL,ALTVM,AVCL,AVCR,AVM,TCCQNT,  
ORCLCON,TJETVM,FCNCON,GR,ALCL,ALTVM,AVCL,AVCR,AVM,TCCQNT,  
EVOICL,VOIRA,VOIEN,VOICR,VOITQ,ALCL,ALTVM,AVCL,AVCR,AVM,TCCQNT,  
GCLIV(4),NAF(3),NCLI(3),CHPCR1,BHPCR2,BHPTQ2,BHPTQ3,NN,  
HVJV(4),BETA(27),ETAV(27),VMLT,  
ITJETM1,TJETM2,TJETC1,TJETC2,FCN1,FCN2,BHPLIM,AENDUR,VMAX,BETA,  
BETA,ETAV(27),VMLT,

CCCC







```

1  JETAVM, BETAVM, VCRKTS, ETACR, BETACR, RANGE, ENDUR, RC, VCLKTS, ETACL, MM,
2  KBETACL, GRS, DS, AFS, CLIS, TOFAC, CRFAC, VMFAC, RAFAC, ENFAC, CLFAC, EFFM,
3  LDCLMV(4,5), VJVFT(5), EMACHV(4,5), FSUBTV(4,5), VJVFT(7), FSUBTV(7), TOLT,
4  MEPAV(4,5), EPAALT(4,5), SHPV(5), NUMBLS, VCRLT, COORD(4,4), COORDF(4)
5  DIMENS ION, M(3), F(3)
6  IF(ALT.GT.35332.)FSURC=.869
7  IF(ALT.LE.35332.)FSURC=1.-3.71E-06*ALT
8  VMACH=FSURC*VKTS/662.
9  CLI=CLI*CSTI
10 CALL NONLIN(CLI, V(NCLI(1)), CLIV(NCLI(2)), CLIV(NCLI(3)), DELMV(NCLI(1)
11 ), DELMV(NCLI(2)), DELMV(NCLI(3)), CLI, DELM)
12 CLI=CLI/CSTI
13 EFFM=VMACH+DELM
14 DO I=1,4
15 IF(VJ.LT.VJVFT(1))GO TO 2
16 IF(VJ.GE.VJVFT(1)).AND.VJ.LE.VJVFT(I+1))GO TO 2
17 CONTINUE
18 IF(I.EQ.4)GO TO 3
19 NJ(1)=I+1
20 NJ(2)=I+1
21 NJ(3)=I+2
22 GO TO 4
23 NJ(1)=I+1
24 NJ(2)=I+1
25 NJ(3)=I-1
26 DO I=1,3
27 J=1
28 IF(EFFM.LT.EMACHV(1,NJ(I)))GO TO 6
29 DO J=1,3
30 IF(EFFM.GE.EMACHV(J,NJ(I)).AND.EFFM.LE.EMACHV(J+1,NJ(I)))GO TO 6
31 CONTINUE
32 IF(J.EQ.3)GO TO 8
33 M(1)=J
34 M(2)=J+1
35 M(3)=J+2
36 GO TO 5
37 M(1)=J+1
38 M(2)=J
39 M(3)=J-1
40 CALL NONLIN(EMACHV(M(1),NJ(I)), EMACHV(M(2),NJ(I)), EMACHV(M(3),NJ(I)
41 ), FSUBTV(M(1),NJ(I)), FSUBTV(M(2),NJ(I)), FSUBTV(M(3),NJ(I)),
42 EFFM, F(I))
43 IF(F(I).GT.1.)F(I)=1.
44 CONTINUE
45 CALL NONLIN(VJVFT(NJ(1)), VJVFT(NJ(2)), VJVFT(NJ(3)), F(1), F(2), F(3),
46 VJ, FSUBT)
47 IF(FSUBT.GT.1.)FSURT=1.
48 DO I=1,6

```



```

10 IF(VJ.GE.VJVFB(I).AND.VJ.LE.VJVFB(I+1))GO TO 11
11 CONTINUE
12 IF(I.EQ.6)GO TO 12
    NJ(1)=I+1
    NJ(2)=I+2
    NJ(3)=I+3
    GO TO 13+1
12 NJ(1)=I+1
    NJ(3)=I-1
    CALL NONLIN(VJVFB(NJ(1)),VJVFB(NJ(2)),VJVFB(NJ(3)),
13 FSUBBV(NJ(2)),FSUBBV(NJ(3)),VJ,FSUBB)
    FSUBB=.94*FSUBB
    RETURN
END

```

[illegible]

```

16 WRITE(6,1000)
1000 FORMAT(' THIS PROGRAM OPTIMIZES THE PROPELLER FOR A GIVEN AIRCRAFT

```























[illegible]





```

1063 IF(CRCONT.EQ.0.)WRITE(6,1047)
1064 WRITE(6,1068)VMCONT
1065 IF(VMCONT.EQ.0.)WRITE(6,1047)
1066 FORMAT(/'+MAX. ALLOWABLE TAKEOFF DISTANCE ='F8.1,' FT/MIN')
1067 FORMAT(/'+LOWEST ALLOWABLE MAX. RATE OF CLIMB ='F7.1,' FT/MIN')
1068 FORMAT(/'+MINIMUM ALLOWABLE RANGE AT CRUISE CONDITIONS ='F8.1,' N
1069 MI')
1066 FORMAT(/'+MINIMUM ALLOWABLE ENDURANCE AT CRUISE CONDITIONS ='
1067 F5.1,' HRS')
1067 FORMAT(/'+MINIMUM ALLOWABLE CRUISE SPEED ='F6.1,' KTS')
1068 FORMAT(/'+LOWEST ALLOWABLE MAX. SPEED ='F6.1,' KTS')
1069 WRITE(6,1040)
1070 READ(5,1005)NSTEP
1071 GO TO(1,2,3,4,5,6,7),NSTEP
1072 WRITE(6,1069)
1073 FOR DATA(//, STEP 5: PROPELLER CONSTRAINTS'//, PLEASE TYPE IN REQUIR
1074 ED DIAMETER IN PROPER UNITS...ALWAYS INCLUDE A DECIMAL'//, MAX. BLADE
1075 2 DIAD(5,1002)DMAX
1076 WRITE(6,1004)DMAX
1077 WRITE(6,1070)
1078 FOR DATA(//, THE FOLLOWING PROP CONSTRAINTS ARE OPTIONAL'//
1079 1, IF NEEDED, THE OPTIMUM VALUE OF EACH QUANTITY WILL BE DET
1080 2 RT MINED'//, TYPE "0." AS THE VALUE OF ANY CONSTRAINT WHICH YOU DO N
1081 3 RT WISH'//, TO SPECIFY')
1082 WRITE(6,1071)
1083 FOR DATA(//, NUMBER OF BLADES = ?')
1084 14 WRITE(6,1005)NUMBLS
1085 1071 READ(5,1005)NUMBLS
1086 IF(NUMBLS.NE.0.AND.(NUMBLS.LT.2.OR.NUMBLS.GT.4))GO TO 10
1087 WRITE(6,1005)GRS
1088 READ(5,1002)GRS
1089 WRITE(6,1072)
1090 FOR DATA(//, BLADE DIAMETER = ? (FT)')
1091 1072 READ(5,1002)DS
1092 WRITE(6,1074)
1093 FOR DATA(//, ACTIVITY FACTOR = ?')
1094 1074 READ(5,1002)AFS
1095 IF(AFS.NE.0..AND.((NUMBLS.EQ.2.AND.AFS.GT.120.).OR.(AFS.LT.80..OR.
1096 1 AFS.GT.220.)))GO TO 11
1097 WRITE(6,1075)
1098 FOR DATA(//, INTEGRATED LIFT COEFFICIENT = ?')
1099 1075 READ(5,1002)CLIS
1100 IF(CLIS.NE.0..AND.((NUMBLS.EQ.2.AND.CLIS.LT..3).OR.(CLIS.LT..15
1101 1 OR.CLIS.GT..12
1102 1 OR.CLIS.GT..1077)
1103 1077 FOR DATA(//, END OF STEP 5...OPTICNAL BLADE CONSTRAINTS FOLLOW
1104 1(CHECK VALUES CAREFULLY FOR ACCURACY)')

```













```

55 J1=J+(J-1)
J2=2*J
NALT(J1)=I
NALT(J2)=I+1
60 CONTINUE
CALL LIN(EPAALT(NALT(1),NHP(1)),EPAALT(NALT(2),NHP(1)),EPAV(NALT(1),NHP(1)),EPAV(NALT(2),NHP(1)),ALTVM,EPA1)
1)NHP(1))EPAV(NALT(3),NHP(2)),EPAALT(NALT(4),NHP(2)),EPAV(NALT(3),NHP(2)),EPAV(NALT(4),NHP(2)),ALTVM,EPA2)
1)NHP(2))EPAV(NALT(1),NHP(1)),SHPV(NHP(1)),SHPV(NHP(2)),BHPVM,EPA)
CALL LIN(EPA1,EPA2,EPA=1000.
IF(EPA.LE.0.)EPA=1000.
IF(CLIIS.EQ.0.)CLI=CLIS
IF(CLIIS.NE.0.)AF=80.
IF(AFS.EQ.0.)AF=AFS
IF(AFS.NE.0.)AF=AFS
IF(CS.NE.0.)GO TO 63
D=SQRT(EPA/(FLOAT(NUMBL)*AF))
IF(D.LE.DMAX)GO TO 200
D=DMAX
NE.0.)GO TO 200
IF(AFS.NE.0.)GO TO 200
AF=EPA/(FLOAT(NUMBL)*(D**2))
AF=(NUMBL*NE.2.*AND.AF.LE.80.*AND.AF.LE.220.).CR.(NUMBL*EQ.2.*AND.AF
1)GE.80.*AND.AF.LE.120.))GO TO 200
1)GE.80.*AND.AF.LE.120.))GO TO 66
IF(AF.LT.80.)GO TO 66
IF(NUMBL*EQ.2)AF=120.
IF(NUMBL*NE.2)AF=220.
GO TO 200
66 AF=80.
IF(GRS.EQ.0.)GR=(D*RPVM)/(50.7*AVM)
200 IF(GRS.NE.0.)GR=GRS
ARG(1)=GR/CSTG
ARG(2)=D
ARG(3)=AF/CSTA
ARG(4)=CLI/CST1
CALL DIRECT(ARG,4,FMIN,DELCAP,.25, .05,FUNCT,KONVRG,500,-1)
15 IF(NUMBL.NE.4)GO TO 71
IF(NUMBL=3
NUMBL=8
GO TO 72
71 IF(NUMBL*EQ.2)GO TO 72
IF(COORDF(3).LE.COORDF(4))GO TO 73
IF(COORDF(3).LE.COORDF(4))GO TO 73
DO 74 I=1,4
74 ARG(I)=COORD(4,I)
NUMBL=4
GO TO 75
73 NUMBL=2
GO TO 8
72 IF(COORDF(2).LE.COORDF(3))GO TO 76

```

INP04180  
INP04190  
INP04200  
INP04210  
INP04220  
INP04230  
INP04240  
INP04250  
INP04260  
INP04270  
INP04280  
INP04290  
INP04300  
INP04310  
INP04320  
INP04330  
INP04340  
INP04350  
INP04360  
INP04370  
INP04380  
INP04390  
INP04400  
INP04410  
INP04420  
INP04430  
INP04440  
INP04450  
INP04460  
INP04470  
INP04480  
INP04490  
INP04500  
INP04510  
INP04520  
INP04530  
INP04540  
INP04550  
INP04560  
INP04570  
INP04580  
INP04590  
INP04600  
INP04610  
INP04620  
INP04630  
INP04640  
INP04650



```

77 DO 77 I=1,4
   ARG(I)=COORD(3,I)
   GO TO 75
76 DO 76 I=1,4
   ARG(I)=COORD(2,I)
   NUMBL=75
   GO TO 75
75 DO 75 I=1,4
   ARG(I)=COORD(NUMBL,I)
   NN=1
   MM=1
   DUM=FUNCT(ARG)
   WRITE(6,2000) THIS,PO
2000 FORMAT(//,"AT THIS PO
      1ON, OF STEP")
      2ER, OF STEP")
      GO TO (1,2,3,4,5,6,7)
      RETURN
      END

```

```

2000 9 WRITE(6,2000)
      10 FORMAT(//,A1,THIS POINT,IF YOU WISH TO TERMINATE PROGRAM OPERATI
      20 ION,TYPE STEP,IF YOU WISH TO RETURN TO AN INPUT STEP,TYPE NUMB
      30 ER OF STEP)
      40 READ(5,1005)NSTEP
      50 GO TO (1,2,3,4,5,6,7),NSTEP
      60 RETURN
      70 END

```

[illegible]

EEVVAA00180  
EEVVAA00190  
EEVVAA00200  
EEVVAA00210  
EEVVAA00220  
EEVVAA00230  
EEVVAA00240  
EEVVAA00250  
EEVVAA00260  
EEVVAA00270

```
CL=CL*CSI
WRITE(6,56)NUMBL,GR,D,AF,CLI,CCORDE(NUMBL)
```







```

56 FORMAT(' OPTIMUM PROPELLER :',' NUMBER OF BLADES ='12',' GEAR RATE,EVAOC280
110 ='F6.2',' DIAMETER ='F6.2',' FT',' ACTIVITY FACTOR ='F6.1',' INTEGE,EVAOC290
2RA=GR/CSTI COEFFICIENT ='F6.3',' FUNCTION VALUE ='E15.7) EVAOC300
GR=GR/CSTI EVAOC310
AF=AF/CSTI EVAOC320
CLI=CLI/CSTI EVAOC330
TOFAC=C. EVAOC340
CLFAC=C. EVAOC350
CRFAC=0. EVAOC360
VMFAC=0. EVAOC370
VMFAC=0. EVAOC380
ENFAC=0. EVAOC390
TOLT=0. EVAOC400
VMLT=0. EVAOC410
VCRLT=0. EVAOC420
VCRLT=0. EVAOC430
ATOL=18. EVAOC440
E.EQ.2) FCCN=FCON1 EVAOC450
IF(N TYPE=FUEL/(FLOAT(NUMENG)*FCON)-.75 EVAOC460
AENDUR=AVCR#AENDUR SIGMA(ALTCL)*WAREA*((1.689*AVCL)**3)/550. EVAOC470
ARANGE=AVCR#RHOSL*SIGMA(ALTCL)*WAREA*((1.689*AVCL)**3)/550. EVAOC480
IF(N TYPE=EQ.2) BHPCL=RHPT02 EVAOC490
AAVHP=FLOAT(NUMENG)*BHPCL*.8 EVAOC500
ARC=(AAVHP-A.1) TJET=0. EVAOC510
IF(N TYPE=EQ.1) TJET=0. EVAOC520
IF(N TYPE=EQ.1) GO TO 93 EVAOC530
CALL NONLIN(0.,100.,400.,BHP01,BHPT02,BHPT03,AVM,BHP2) EVAOC540
CALL LIN(C.,1000.,BHP2,BHPM,ALT0,BHP3) EVAOC550
ALTCOR=BHPT01+ALTCOR EVAOC560
RHPT0=BHPT01 EVAOC570
TJET=TJETM1 EVAOC580
IF(BHPT0.GT.BHPLIM) BHPT0=BHPLIM EVAOC590
IF(BHPT0.GT.BHPLIM) BHPT0=BHPLIM EVAOC600
RPMTO=RPM EVAOC610
CPTO=BHPT0/(2000.*SIGMA(ALT0))*((RPMTO/(1000.*GR*CSTG))**3)*((C/1C EVAOC620
1.)*.5)) EVAOC630
CPT01=CPTO EVAOC640
FCOEF=.025 EVAOC650
CLOPT=.5*3.141593*FCOEF*E*AR EVAOC660
CD=CCPTO+((CLOPT**2)/(3.141593*AR*E)) EVAOC670
NB=NUMBL-1 EVAOC680
IF(NUMBL-1 GE.3) GO TO 97 EVAOC690
DO 98 I=1,3 EVAOC700
CLIV(I)=.3+.2*(FLOAT(I)-1.) EVAOC710
J2=2 EVAOC720
GO TO 54 EVAOC730
97 CLIV(1)=.15 EVAOC740
DO 99 I=2,4 EVAOC750
CLIV(I)=.3+.2*(FLOAT(I)-1.) EVAOC760
99 CLIV(I)=.3+.2*(FLOAT(I)-1.) EVAOC770

```



EVA00C760  
 EVA00C770  
 EVA00C780  
 EVA00C790  
 EVA00C800  
 EVA00C810  
 EVA00C820  
 EVA00C830  
 EVA00C840  
 EVA00C850  
 EVA00C860  
 EVA00C870  
 EVA00C880  
 EVA00C890  
 EVA00C900  
 EVA00C910  
 EVA00C920  
 EVA00C930  
 EVA00C940  
 EVA00C950  
 EVA00C960  
 EVA00C970  
 EVA00C980  
 EVA00C990  
 EVA01000  
 EVA01010  
 EVA01020  
 EVA01030  
 EVA01040  
 EVA01050  
 EVA01060  
 EVA01070  
 EVA01080  
 EVA01090  
 EVA01100  
 EVA01110  
 EVA01120  
 EVA01130  
 EVA01140  
 EVA01150  
 EVA01160  
 EVA01170  
 EVA01180  
 EVA01190  
 EVA01200  
 EVA01210  
 EVA01220  
 EVA01230

```

J2=3
IF(NUMBL-3)94,2,13
DO 5 I=1,8
AFVST(I)=80.+20.*(FLOAT(I)-1.)
13 5 J=7
AFVFLT(1)=80.
DO 42 I=2,5
AFVFLT(I)=100.+(40.*(FLOAT(I)-2.))
42 42 J1=4
GO TO 6
DO 3 I=1,3
AFVST(I)=80.+20.*(FLOAT(I)-1.)
2 3 DO 4 I=4,7
AFVST(I)=80.+20.*(FLOAT(I)-1.)
4 4 J=6
AFVFLT(1)=80.
AFVFLT(2)=100.
AFVFLT(3)=180.
AFVFLT(4)=220.
J1=3
DO 94 TO 96 I=1,3
94 DO 95 I=1,3
95 AFVST(I)=80.+20.*(FLOAT(I)-1.)
J=2
DO 96 I=1,3
96 AFVFLT(I)=AFVST(I)
J1=2
DO 8 I=1,3
IF((AF*CSA).LT.AFVST(1))GO TO 9
IF((AF*CSA).GE.AFVST(1).AND.(AF*CSA).LE.AFVST(I+1))GO TO 9
8 9 CONTINUE
IF(I.EQ.J)GO TO 10
NAF(1)=I+1
NAF(2)=I+2
NAF(3)=I+1
GO TO 11
10 NAF(1)=I+1
NAF(2)=I-1
NAF(3)=I-1
DO 14 I=1,J2
IF((CLIV(I)*CSTI).LT.CLIV(1))GO TO 15
IF((CLIV(I)*CSTI).GE.CLIV(1).AND.(CLIV(I+1))GO TO 15
11 14 CONTINUE
IF(I.EQ.J2)GO TO 18
14 15 IF(I(1))=I+1
NCL I(2)=I+2
NCL I(3)=I+2
GO TO 19
  
```



```

18 NCLI(1)=I+1
19 NCLI(2)=I
20 NCLI(3)=I-1
21 IF(MM.EQ.0.AND.VOITO.EQ.0..AND.TCCONT.EQ.0.)GO TO 121
24 K3=1
DO 22 I=1,3
DO 22 J=1,3
DO 22 K=1,3
IF(CPTO.LE.STATCP(I,NCLI(K2),NAF(K1),NB))GO TO 32
IF(CPTO.GE.STATCP(I,NCLI(K2),NAF(K1),NB))GO TO 23
1 NCLI(K2),NAF(K1),NB).EQ.0.)GO TO 87
IF(STATCP(I+1,NCLI(K2),NAF(K1),NB).EQ.0.)GO TO 87
GO TO 22
23 CALL LIN(STATCP(I,NCLI(K2),NAF(K1),NB),STATCP(I+1,NCLI(K2),NAF(K1),NB),
1,NB),STATCT(I,NCLI(K2),NAF(K1),NB),STATCT(I+1,NCLI(K2),NAF(K1),NB),
2,CPTO,CT(K3))
GO TO 88
87 CALL NCNLI(STATCP(I-2,NCLI(K2),NAF(K1),NB),STATCP(I-1,NCLI(K2),
1,NAF(K1),NB),STATCP(I,NCLI(K2),NAF(K1),NB),STATCT(I-2,NCLI(K2),
2,NAF(K1),NB),STATCT(I-1,NCLI(K2),NAF(K1),NB),STATCT(I,NCLI(K2),
3,NAF(K1),NB),CPTO,CT(K3))
88 K3=K3+1
GO TO 21
32 CT(K3)=C.
GO TO 21
22 K3=K3+1
GO TO INUEE
21 CONTINUE
20 CONTINUE
CLI=CLICSTA
AF=AF*CSA
26 CALL NCNLI(CLIV(NCLI(1)),CLIV(NCLI(2)),CLIV(NCLI(3)),CT(1),CT(2),
1,CT(3),CT(1),CT(1))
CALL NCNLI(CLIV(NCLI(1)),CLIV(NCLI(2)),CLIV(NCLI(3)),CT(4),CT(5),
1,CT(6),CT(2),CT(2))
CALL NCNLI(CLIV(NCLI(1)),CLIV(NCLI(2)),CLIV(NCLI(3)),CT(7),CT(8),
1,CT(9),CT(3),CT(3))
CALL NCNLI(CLIV(NCLI(1)),CLIV(NCLI(2)),CLIV(NCLI(3)),CT(1),CT(1),
31,CT(2),CT(2),CT(2))
CLI=CLICSTA
AF=AF/CSA
28 IF(CTTC.LE.0.)GO TO 33
TSTAT=FLOAT(NUMENG)*((CTTO*6HPTO*33000.)/((RPMTD/(GR*CSG)*D))+
1,TJET)
121 CO 43 I=1,J1
IF((AF*CSA).LT.AFVELT(1))GO TO 44
IF((AF*CSA).GE.AFVELT(1)).AND.(AF*CSA).LE.AFVFLT(I+1))GO TO 44
43 CONTINUE

```























```

IF(CLCONT.NE.0..AND.RC.LT.CLCONT)CLFAC=1.
VCLKTS=VKTS
IF((GRS*DS*AFS*CLIS*FLCAT(NUMBLS)).NE.0..OR.NN.EQ.1)
1WRITE(6,2004)RC,VCLKTS,BETACL,ETACL,
2BHPCL,TJET
2004 1F6.0,3//2X,'J',7X,'FT',8X,'FB',8X,'RHP',6X,
2= 'F4.1,1, DEG',1, PROP EFFICIENCY
3TJET//F5.3,4F10.4,F10.0,F9.0)
123 IF(TOLT.EQ.1..OR.VMLT.EQ.1.)GO TO 102
GO TO 91
83 VCRLT=1.
IF((GRS*DS*AFS*CLIS*FLCAT(NUMBLS)).EQ.0..AND.NN.EQ.0)GO TO 100
WRITE(6,2051)
GO TO 100
2051 1ND CONDITIONS')
85 VMLT=1.
IF((GRS*DS*AFS*CLIS*FLCAT(NUMBLS)).EQ.0..AND.NN.EQ.0)GO TO 100
WRITE(6,2050)
GO TO 101
2050 1ER AND CONDITIONS')
91 IF(VMAX.EQ.0.)VMAX=1.
IF(VCRKTS.NE.0.)GO TO 124
VCRKTS=1.
RANGUR=1.
IF(RC.EQ.0.)RC=1.
IF((GRS*DS*AFS*CLIS*FLCAT(NUMBLS)).NE.0.)GO TO 92
FUNCTION=(VOIRANGE/RANGE)+(VOICR*AVCR/VCRKTS)+
1(VOIRANGE/RANGE)+(VOIRANGE/RANGE)+(VOICR*AVCR/VCRKTS)+
2(VOIRANGE/RANGE)+(VOIRANGE/RANGE)+(VOICR*AVCR/VCRKTS)+
3(VOIRANGE/RANGE)+(VOIRANGE/RANGE)+(VOICR*AVCR/VCRKTS)+
102 1(RAFAC*1.EQ.1..AND.CRAFAC.NE.1..AND.NN.EQ.0).OR.(MM.
1AND.CRAFAC.NE.1..AND.NN.EQ.0).OR.(MM.
2EQ.0..AND.NN.EQ.0)GO TO 92
IF((GRS*DS*AFS*CLIS*FLCAT(NUMBLS)).NE.0..OR.NN.EQ.1)WRITE(6,2052)
2052 1STRAIN')
92 1END

```

EVAC3640  
 EVAC3650  
 EVAC3660  
 EVAC3670  
 EVAC3680  
 EVAC3690  
 EVAC3700  
 EVAC3710  
 EVAC3720  
 EVAC3730  
 EVAC3740  
 EVAC3750  
 EVAC3760  
 EVAC3770  
 EVAC3780  
 EVAC3790  
 EVAC3800  
 EVAC3810  
 EVAC3820  
 EVAC3830  
 EVAC3840  
 EVAC3850  
 EVAC3860  
 EVAC3870  
 EVAC3880  
 EVAC3890  
 EVAC3900  
 EVAC3910  
 EVAC3920  
 EVAC3930  
 EVAC3940  
 EVAC3950  
 EVAC3960  
 EVAC3970  
 EVAC3980  
 EVAC3990  
 EVAC4000  
 EVAC4010  
 EVAC4020  
 EVAC4030  
 EVAC4040  
 EVAC4050  
 EVAC4060





**APPENDIX B**  
**SAMPLE COMPUTER OUTPUT**



EXECUTION BEGINS...  
DATA NOW BEING READ  
DATA HAS BEEN READ  
THIS PROGRAM OPTIMIZES

THE PROPELLER FOR A GIVEN AIRCRAFT UNDER SPECIFIED CONDITIONS

PLEASE TYPE IN THE REQUESTED INFORMATION, FOLLOWING THE DIRECTIONS CAREFULLY

INPUT ROUTINE...

STEP 1: AIRCRAFT DATA

STEP 2: ENGINE DATA

STEP 3: AIRCRAFT ENVIRONMENT AND ANTICIPATED PERFORMANCE

STEP 4: AIRCRAFT PERFORMANCE CONSTRAINTS (OPTIMIZATION ONLY)

STEP 5: PROPELLER CONSTRAINTS

STEP 6: OPTIMIZATION CRITERIA (OPTIMIZATION ONLY)

STEP 7: END OF INPUT ROUTINE...PROPELLER EVALUATION OR OPTIMIZATION

STEP 1: AIRCRAFT DATA

PLEASE TYPE IN AIRCRAFT DATA AS CALLED FOR IN THE PROPER UNITS....INCLUDE DECIMAL

DESIGN GROSS WEIGHT = ? (LBS.)  
105000.

WING AREA = ? (SQ. FT.)  
1300.

NUMBER OF ENGINES = ?  
4.

ASPECT RATIO = ?  
7.5

PARASITIC DRAG COEFFICIENT = ? (TAKEOFF CONFIGURATION)  
.05

PARASITIC DRAG COEFFICIENT = ? (CRUISE CONFIGURATION)  
.0247



WING EFFICIENCY FACTOR = ? (SMALL E)  
.98

FUEL CAPACITY = ? (LBS.)  
29370.

TAKEOFF SPEED = ? (KTS TAS)  
121.

END OF STEP 1....AIRCRAFT DATA FOLLOW: (CHECK VALUES CAREFULLY FOR ACCURACY)

WEIGHT = 105000.0 LBS.

WING AREA = 1300.0 SQ. FT.

NUMBER OF ENGINES = 4

ASPECT RATIO = 7.50

PARASITIC DRAG COEF. (TAKEOFF) = 0.050 PARASITIC DRAG COEF. (CRUISE) = 0.025

WING EFFICIENCY FACTOR = 0.980 FUEL CAPACITY = 29370.0 LBS.

TAKEOFF SPEED = 121. KTS TAS

AT THIS POINT, TYPE "0." IF YOU WISH TO CONTINUE  
IF YOU WISH TO RETURN OR ADVANCE TO ANOTHER STEP, TYPE NUMBER OF STEP  
0.

STEP 2: ENGINE DATA

PLEASE TYPE IN REQUIRED ENGINE DATA IN PROPER UNITS....ALWAYS INCLUDE A DECIMAL  
ENTER ENGINE CHARACTERISTICS AT WHATEVER AIR DENSITY THE AIRCRAFT PERFORMANCE IS TO BE OPTIMIZED,  
FOR THAT PARTICULAR PORTION OF ITS MISSION

RECIPROCATING (1) OR TURBO-PROP (2) ENGINE ?....(TYPE NUMBER CORRESPONDING TO CORRECT CHOICE)  
2.

ENGINE OPERATING RPM = ?  
13820.



SHP (PER ENGINE) AT CRUISE ALTITUDE AND CRUISE POWER SETTING,  
FOR ANTICIPATED CRUISE SPEED (TAS) AND 50 KTS ABOVE THIS SPEED, RESPECTIVELY, = ? (HIT RETURN BETWEEN ENTRIES)  
1755.  
1861.

ENTER SHP AT MAX. POWER SETTING (POWER FOR TAKEOFF AND MAX. SPEED)  
FOR ANTICIPATED MAX. SPEED (TAS) AND 10,000 FT MSL ALTITUDE  
SHP AT ABOVE CONDITIONS = ?  
4637.

ENTER SEA LEVEL SHP FOR MAX. POWER SETTING AT 0., 100, AND 400 KTS (TAS), RESPECTIVELY  
SHP UNDER ABOVE CONDITIONS = ? (HIT RETURN AFTER EACH SHP ENTRY)  
4527.  
4712.  
5790.

SEA LEVEL JET THRUST (LBS PER ENGINE) FOR MAX. POWER SETTING AT 0. AND 100. KTS (TAS), RESPECTIVELY, = ?  
(HIT RETURN AFTER EACH ENTRY)  
639.  
533.

SEA LEVEL JET THRUST FOR CRUISE POWER SETTING AT 0. AND 100. KTS (TAS), RESPECTIVELY, = ? (HIT RETURN AFTER EACH ENTRY)  
462.  
353.

ENTER FUEL FLOW (LBS/HR) FOR CRUISE POWER AND ALTITUDE AT ANTICIPATED CRUISE SPEED (TAS)  
AND 50 KTS ABOVE THIS SPEED, RESPECTIVELY  
FUEL FLOW AT ABOVE CONDITIONS = ? (HIT RETURN AFTER EACH ENTRY)  
1035.  
1063.

LIMITING SHP FOR CONTINUOUS OPERATION = ?  
4500.





END OF STEP 2....ENGINE DATA (PER ENGINE) FOLLOW (CHECK VALUES CAREFULLY FOR ACCURACY)

ENGINE OPERATING RPM = 13820.0

SHP AT CRUISE POWER AND ALTITUDE = 1755.0 AT CRUISE SPD AND = 1861.0 AT CRUISE SPD + 50 KTS

SHP AT MAX. SPEED POWER AND 10,000 FT ALTITUDE FOR ANTICIPATED MAX. SPEED = 4637.0

SEA LEVEL SHP AT MAX. POWER = 4527.0 AT 0. KTS, 4712.0 AT 100 KTS, 5790.0 AT 400 KTS

SEA LEVEL JET THRUST FOR MAX. POWER = 639.0 LBS AT 0. KTS, 533.0 LBS AT 100 KTS

SEA LEVEL JET THRUST FOR CRUISE POWER = 462.0 LBS AT 0. KTS, 353.0 LBS AT 100 KTS

FUEL FLOW FOR CRUISE POWER AND ALTITUDE = 1035.0 LBS/HR AT CRUISE SPEED, 1063.0 LBS/HR AT CRUISE SPEED + 50 KTS

LIMITING SHP FOR CONTINUOUS OPERATION = 4500.0

AT THIS POINT, TYPE "0." IF YOU WISH TO CONTINUE  
IF YOU WISH TO RETURN OR ADVANCE TO ANOTHER STEP, TYPE NUMBER OF STEP  
0.

STEP 3: AIRCRAFT ENVIRONMENT AND ANTICIPATED PERFORMANCE  
PLEASE TYPE IN REQUIRED DATA IN PROPER UNITS....ALWAYS INCLUDE A DECIMAL

PLEASE TYPE IN ALTITUDES (FT. MSL) AT WHICH AIRCRAFT PERFORMANCE IS TO BE EVALUATED  
AT TAKEOFF, CLIMB, CRUISE, AND MAXIMUM SPEED....(SHOULD CORRESPOND WITH ENGINE DATA)

ALTITUDE AT TAKEOFF = ? (FT. MSL)  
0.

ALTITUDE AT CLIMB = ?  
0.

CRUISE ALTITUDE = ?  
15000.



ALTITUDE AT MAX. SPEED = ?  
10000.1

ANTICIPATED AIRCRAFT SPEEDS (TAS):

CLIMB SPEED = ? (KTS)  
235.

CRUISE SPEED = ? (KTS)  
250.

MAX. SPEED = ? (KTS)  
386.

END OF STEP 3....ENVIRONMENT AND ANTICIPATED SPEED DATA FOLLOW (CHECK VALUES CAREFULLY FOR ACCURACY)

ALTITUDE AT TAKEOFF = 0.0 FT MSL ALTITUDE AT CLIMB = 0.0 FT MSL

CRUISE ALTITUDE = 15000.0 FT MSL ALTITUDE AT MAX. SPEED = 10000.1 FT MSL

CLIMB SPEED = 235.0 KTS (TAS) CRUISE SPEED = 250.0 KTS (TAS) MAX. SPEED = 386.0 KTS (TAS)

AT THIS POINT, TYPE "0." IF YOU WISH TO CONTINUE  
IF YOU WISH TO RETURN OR ADVANCE TO ANOTHER STEP, TYPE NUMBER OF STEP  
0.

STEP 4: PERFORMANCE CONSTRAINTS  
PLEASE TYPE IN REQUIRED DATA IN PROPER UNITS....ALWAYS INCLUDE A DECIMAL

TYPE "0." AS THE VALUE OF ANY CONSTRAINT WHICH YOU DO NOT WISH TO SPECIFY

MAXIMUM ALLOWABLE TAKEOFF DISTANCE = ? (FT)  
2500.



LOWEST ALLOWABLE MAXIMUM RATE OF CLIMB = ? (FT/MIN)

0.

MINIMUM ALLOWABLE RANGE AT CRUISE CONDITIONS = ? (N MI)

0.

MINIMUM ALLOWABLE ENDURANCE AT CRUISE CONDITIONS = ? (HRS)

0.

MINIMUM ALLOWABLE CRUISE SPEED = ? (KTS TAS)

0.

LOWEST ALLOWABLE MAXIMUM SPEED = ? (KTS TAS)

0.

END OF STEP 4.....PERFORMANCE CONSTRAINTS FOLLOW (CHECK VALUES CAREFULLY FOR ACCURACY)

MAX. ALLOWABLE TAKEOFF DISTANCE = 2500.0 FT/MIN

LOWEST ALLOWABLE MAX. RATE OF CLIMB = 0.0 FT/MIN .....(UNSPECIFIED)

MINIMUM ALLOWABLE RANGE AT CRUISE CONDITIONS = 0.0 N MI .....(UNSPECIFIED)

MINIMUM ALLOWABLE ENDURANCE AT CRUISE CONDITIONS = 0.0 HRS .....(UNSPECIFIED)

MINIMUM ALLOWABLE CRUISE SPEED = 0.0 KTS .....(UNSPECIFIED)

LOWEST ALLOWABLE MAX. SPEED = 0.0 KTS .....(UNSPECIFIED)

AT THIS POINT, TYPE "0." IF YOU WISH TO CONTINUE  
IF YOU WISH TO RETURN OR ADVANCE TO ANOTHER STEP, TYPE NUMBER OF STEP  
0.0.@@

STEP 5: PROPELLER CONSTRAINTS  
PLEASE TYPE IN REQUIRED DATA IN PROPER UNITS.....ALWAYS INCLUDE A DECIMAL

MAX. BLADE DIAMETER FOR STRUCTURAL OR GROUND CLEARANCE = ? (FT)  
13.5



MAX. BLADE DIAMETER = 13.50 FT

THE FOLLOWING PROP CONSTRAINTS ARE OPTIONAL  
IF NOT SPECIFIED, THE OPTIMUM VALUE OF EACH QUANTITY WILL BE DETERMINED  
TYPE "0." AS THE VALUE OF ANY CONSTRAINT WHICH YOU DO NOT WISH TO SPECIFY

NUMBER OF BLADES = ?  
0.

GEAR RATIO = ? (ENGINE RPM/PROP RPM)  
13.54

BLADE DIAMETER = ? (FT)  
0.

ACTIVITY FACTOR = ?  
0.

INTEGRATED LIFT COEFFICIENT = ?  
0.

END OF STEP 5....OPTIONAL BLADE CONSTRAINTS FOLLOW (CHECK VALUES CAREFULLY FOR ACCURACY)

GEAR RATIO = 13.54 (ENGINE RPM/PROP RPM)  
NUMBER OF BLADES = 0 ....(UNSPECIFIED)

BLADE DIAMETER = 0.0 FT ....(UNSPECIFIED)

ACTIVITY FACTOR = 0.0 ....(UNSPECIFIED)

INTEGRATED LIFT COEFFICIENT = 0.0 ....(UNSPECIFIED)

AT THIS POINT, TYPE "0." IF YOU WISH TO CONTINUE  
IF YOU WISH TO RETURN OR ADVANCE TO ANOTHER STEP, TYPE NUMBER OF STEP  
0.





STEP 6: OPTIMIZATION CRITERIA  
PLEASE RATE EACH OF THE FOLLOWING PERFORMANCE TRAITS, ON A SCALE FROM 0. TO 10.,  
ACCORDING TO RELATIVE IMPORTANCE TO AIRCRAFT MISSION

VALUES ASSIGNED SHOULD BE RELATIVE ONLY TO THE OTHER VALUES  
ABSOLUTE MAGNITUDE IS ARBITRARY

"VALUE OF IMPORTANCE" OF SHORT TAKEOFF DISTANCE = ?  
0.

V.0.1. OF CLIMB RATE = ?  
0.

V.0.1. OF RANGE = ?  
0.

V.0.1. OF ENDURANCE = ?  
0.

V.0.1. OF CRUISE SPEED = ?  
1.

V.0.1. OF MAX. SPEED = ?  
0.

END OF STEP 6....OPTIMIZATION CRITERIA FOLLOW

(CHECK VALUES CAREFULLY FOR ACCURACY)

V.0.1. OF SHORT TAKEOFF DISTANCE = 0.0  
V.0.1. OF CLIMB RATE = 0.0  
V.0.1. OF RANGE = 0.0  
V.0.1. OF ENDURANCE = 0.0  
V.0.1. OF CRUISE SPEED = 1.0  
V.0.1. OF MAX. SPEED = 0.0

AT THIS POINT, TYPE "0." IF YOU WISH TO CONTINUE  
IF YOU WISH TO RETURN OR ADVANCE TO ANOTHER STEP, TYPE NUMBER OF STEP  
0.



END OF INPUT ROUTINE.....YOU SHOULD HAVE TIME FOR A QUICK CUP OF COFFEE WHILE AWAITING RESULTS

BEGIN 4 BLADE SEARCH

DIRECT SEARCH DELCAP = 0.816000E 00 RHO = 0.250000E 00 DELLC = 0.500000E-01 MAXEVL = 500 KN = -1

MOVE FUNCTION VALUE GEAR RATIO PROP DIAM. ACTIVITY FACTOR INTEG. LIFT COEF.

ORIGIN 0.8650219E 00 13.54 13.50 220.0 0.400

EXPLORE 0.8631015E 00 13.54 13.50 220.0 0.318

PATTERN 0.8631015E 00 13.54 13.50 220.0 0.318

EXPLORE 0.8631015E 00 13.54 13.50 220.0 0.318

EXPLORE 0.8631015E 00 13.54 13.50 220.0 0.318

EXPLORE 0.8630986E 00 13.54 13.50 220.0 0.323

PATTERN 0.8630986E 00 13.54 13.50 220.0 0.323

EXPLORE 0.8630986E 00 13.54 13.50 220.0 0.323

EXPLORE 0.8630978E 00 13.54 13.50 220.0 0.322

PATTERN 0.8630978E 00 13.54 13.50 220.0 0.321

EXPLORE 0.8630971E 00 13.54 13.50 220.0 0.321

PATTERN 0.8630971E 00 13.54 13.50 220.0 0.321

EXPLORE 0.8630971E 00 13.54 13.50 220.0 0.321

END OF 4 BLADE SEARCH... 75 FUNCTION EVALUATIONS PERFORMED

BEGIN 3 BLADE SEARCH

DIRECT SEARCH DELCAP = 0.816000E 00 RHO = 0.250000E 00 DELLC = 0.500000E-01 MAXEVL = 500 KN = -1

MOVE FUNCTION VALUE GEAR RATIO PROP DIAM. ACTIVITY FACTOR INTEG. LIFT COEF.

ORIGIN 0.2562007E 03 13.54 13.50 220.0 0.400

EXPLORE 0.2517228E 03 13.54 13.50 220.0 0.482

PATTERN 0.8662022E 00 13.54 13.50 220.0 0.563

PATTERN 0.8662022E 00 13.54 13.50 220.0 0.563



EXPLORE	0.8662022E 00	13.54	13.50	220.0	0.563
EXPLORE	0.8662022E 00	13.54	13.50	220.0	0.563
EXPLORE	0.8652682E 00	13.54	13.50	215.4	0.568
PATTERN	0.8644297E 00	13.54	13.50	210.8	0.568
PATTERN	0.8644290E 00	13.54	13.50	210.8	0.568
EXPLORE	0.8644268E 00	13.54	13.50	210.8	0.570
PATTERN	0.8644268E 00	13.54	13.50	210.8	0.570
EXPLORE	0.8644268E 00	13.54	13.50	210.8	0.570

END OF 3 BLADE SEARCH... 72 FUNCTION EVALUATIONS PERFORMED

OPTIMUM PROPELLER :

NUMBER OF BLADES = 4  
 GEAR RATIO = 13.54  
 DIAMETER = 13.50 FT  
 ACTIVITY FACTOR = 220.0  
 INTEGRATED LIFT COEFFICIENT = 0.321  
 FUNCTION VALUE = 0.8630978E 00

TAKEOFF DISTANCE = 2209. FT  
 CP (STATIC) = 0.4719  
 CT/CP = 0.835  
 PROP EFFICIENCY (AT LIFTOFF) = .618  
 BLADE ANGLE (.75R) (AT V=0.) = 28.4 DEG

FOLLOWING VALUES ARE CALCULATED AT LIFTOFF :

CP	J	M(EFF)	FT	FB	BHP	TJET
.472	0.8904	0.1678	1.0000	1.0043	4500.	483.

MAXIMUM SPEED = 397.6 KTS  
 BLADE ANGLE (.75R) = 53.8 DEG  
 PROP EFFICIENCY = .837

CP	J	M(EFF)	FT	FB	BHP	TJET



CRUISE SPEED = 289.7 KTS  
 BLADE ANGLE (.75R) = 44.3 DEG  
 PROP EFFICIENCY = .849

CP	J	M(EFF)	FT	FB	BHP	TJET
.324	2.1303	0.3980	1.0000	0.9611	1839.	146.

RANGE (AT CRUISE CONDITIONS AND CRUISE SPEED) = 1853. N MI (45 MIN RESERVE)

ENDURANCE (AT CRUISE POWER AND CONDITIONS) = 6.2 HRS (45 MIN RESERVE)

MAXIMUM RATE OF CLIMB = 3156. FT/MIN

CLIMB SPEED = 205. KTS  
 BLADE ANGLE (.75R) = 40.7 DEG  
 PROP EFFICIENCY = .755

CP	J	M(EFF)	FT	FB	BHP	TJET
.472	1.5104	0.2951	0.9968	0.9522	4500.	379.

AT THIS POINT, IF YOU WISH TO TERMINATE PROGRAM OPERATION, TYPE "0."  
 IF YOU WISH TO RETURN TO AN INPUT STEP, TYPE NUMBER OF STEP

0.  
 IHC0021 STOP 0  
 R; T=91.17/105.46 18.36.21





## LIST OF REFERENCES

1. Goldstein, S. "On the Vortex Theory of Screw Propellers", Proceedings of the Royal Society, A123 p. 440, 1929.
2. McCormick, B. W., Jr., Aerodynamics of V/STOL Flight, p. 73-99, Academic Press, 1967.
3. N.A.C.A. Technical Report 640, The Aerodynamic Characteristic of Full-Scale Propellers Having 2, 3, and 4 Blades of Clark Y and R.A.F. 6 Airfoil Sections, by Hartman and Biermann, 1938.
4. Hooke, R. and Jeeves, T. A., "Direct Search Solution of Numerical and Statistical Problems," Journal of the Association for Computing Machinery, v. 8, p. 212-229, April 1961.
5. Bell, M. and Pile, M. C., "Remark on Algorithm 178, Direct Search," Communications of the Association for Computing Machinery, v. 9, p. 684-685, September 1966.
6. Wilde, D. J., Optimum Seeking Methods, Prentice-Hall, 1964.
7. Generalized Method of Propeller Performance Estimation, Revision 'A' to PDB 6101, Hamilton Standard Division, United Aircraft Corporation, Windsor Locks, Connecticut, June 1963.
8. Dommasch, D. O., Sherby, S. S., and Connolly, T. F., Airplane Aerodynamics, 3d ed., p. 304-343, Pitman, 1961.
9. YP-3C/P-3C Orion Performance Characteristics with T56-A-14 Engines, LR22310, Lockheed California Company, Burbank, California
10. H. S. Specification No. HS 1845 Covering the 54H60-69 Propeller for the Lockheed P3V Airplane, HS 1845, Hamilton Standard Division, United Aircraft Corporation, Windsor Locks, Connecticut, August, 1959.



# INITIAL DISTRIBUTION LIST

	No. Copies
1. Defense Documentation Center Cameron Station Alexandria, Virginia 22314	2
2. Library, Code 0212 Naval Postgraduate School Monterey, California 93940	2
3. Chairman, Department of Aeronautics Naval Postgraduate School Monterey, California 93940	1
4. Professor D. M. Layton, Code 57Ln Department of Aeronautics Naval Postgraduate School Monterey, California 93940	1
5. LTJG Robert L. Shaw, USN 248 Greengate Lane Spartanburg, South Carolina 29302	1
6. Navy Plant Representative Hamilton Standard Division United Aircraft Corporation Windsor Locks, Connecticut 06096	1
7. Navy Plant Representative Lockheed California Company Burbank, California 91503	1



# INITIAL DISTRIBUTION LIST

	No. Copies
1. Defense Documentation Center Cameron Station Alexandria, Virginia 22314	2
2. Library, Code 0212 Naval Postgraduate School Monterey, California 93940	2
3. Chairman, Department of Aeronautics Naval Postgraduate School Monterey, California 93940	1
4. Professor D. M. Layton, Code 57Ln Department of Aeronautics Naval Postgraduate School Monterey, California 93940	1
5. LTJG Robert L. Shaw, USN 248 Greengate Lane Spartanburg, South Carolina 29302	1
6. Navy Plant Representative Hamilton Standard Division United Aircraft Corporation Windsor Locks, Connecticut 06096	1
7. Navy Plant Representative Lockheed California Company Burbank, California 91503	1



## DOCUMENT CONTROL DATA - R &amp; D

(Security classification of title, body of abstract and indexing annotation must be entered when the overall report is classified)

ORIGINATING ACTIVITY (Corporate author) Naval Postgraduate School Monterey, California 93940		2a. REPORT SECURITY CLASSIFICATION Unclassified	
		2b. GROUP	
REPORT TITLE Computerized Aerodynamic Optimization of Aircraft Propellers			
DESCRIPTIVE NOTES (Type of report and, inclusive dates) Master's Thesis; June 1970			
AUTHOR(S) (First name, middle initial, last name) Robert Linford Shaw			
REPORT DATE June 1970	7a. TOTAL NO. OF PAGES 101	7b. NO. OF REFS 10	
3. CONTRACT OR GRANT NO.		9a. ORIGINATOR'S REPORT NUMBER(S)	
4. PROJECT NO.			
		9b. OTHER REPORT NO(S) (Any other numbers that may be assigned this report)	
5. DISTRIBUTION STATEMENT This document has been approved for public release and sale; its distribution is unlimited.			
6. SUPPLEMENTARY NOTES		12. SPONSORING MILITARY ACTIVITY Naval Postgraduate School Monterey, California 93940	
8. ABSTRACT <p>The objective of this thesis was to develop a practical computer system for use of empirical data in the aerodynamic optimization of aircraft propellers. The system was designed for use with the IBM 2741 on-line computer terminal. This program provides instructions to the operator during execution, and allows interaction by the operator for input and alteration of data, and for program instructions.</p> <p>The Lockheed P-3C aircraft was chosen as the subject for test and evaluation of the program. The currently operational propeller of this aircraft was tested to compare the program's prediction of aircraft performance against flight test information. An attempt was then made to select a propeller which would provide better performance under the same constraints as those imposed in design of the operational propeller.</p>			





- Aircraft propeller
- Aerodynamic propeller optimization
- Computerized optimization
- Aircraft propeller selection







1 OCT 74  
JUL 1980

23107  
26018

Thesis 118827  
S43734 Shaw  
c.1 Computerized aerodynamic optimization of aircraft propellers.

1 OCT 74  
JUL 1980

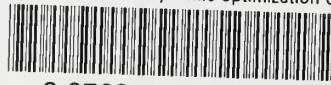
23107  
26018

Thesis  
S43734 Shaw  
c.1 Computerized aerodynamic optimization of aircraft propellers.

118827

thesS43734

Computerized aerodynamic optimization of



3 2768 001 94399 6

DUDLEY KNOX LIBRARY